

Leica MC1

Machine control software Grader

User manual (UM)

Software version: 7.2

Manual version: 8.0
Released: 24/02/2026

Language: English (EN)



Manual type: User manual (UM)

ID: 929453

Manual version: 8.0

Language: English (EN)

Released: 24/02/2026

Made by: LSIF

Content: User workflows relating to the Leica MC1 machine control software for graders.

Software: Leica MC1

Software version: 7.2

Machine type: Grader

Brand: All

Model: All

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Refer to the Leica MC1 "quick guide" for additional legal and safety related requirements.

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Introduction

In this user manual (UM) you will find essential workflows for you to gain success with your machine control solution.

All workflows evolve around MC1 (Software platform) for **grader**, and they cover both 2D and 3D machine control solutions.

Every workflow begins with a short explanation of the task you may be facing, followed by a step by step procedure to help you finish your task successfully.

If you need more in-depth knowledge about any of the workflows, feel free to dive into the user reference manual (URM) for grader. Alternatively, look at the "how to" videos available through QR coded links (See Appendix).

The first chapter in this manual helps you identify your solution. The next chapters focus on either a 2D or 3D solution.

Identify your solution and skip ahead to the chapter relevant to you.

Where can I learn more?

- User reference manual (URM) for grader.
- "How to" videos for grader (See Appendix).

Your machine

Workflows in this chapter focus on your machine as a whole, and are relevant for both 2D and 3D machine control solutions.



2D and 3D solution content:

- **Workflow 01:** Identify your machine control solution
- **Workflow 02:** Define hydraulic performance settings (Gain)
- **Workflow 03:** Adjust height of an electric mast

Workflow 01: Identify your machine control solution

Find out if you have a 2D or 3D machine control solution installed on your machine. Once you know which solution you have to work with, you can skip ahead to the relevant chapter in this manual.

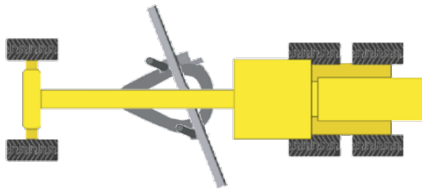
Step 1: Identify which machine control components you have installed on your machine.

Step 2: Identify the source of your position reference (Rotating laser, total station or GNSS).

Step 3: Compare your hardware configuration with the overview on the following two pages:

- Do you have a 2D or 3D solution?

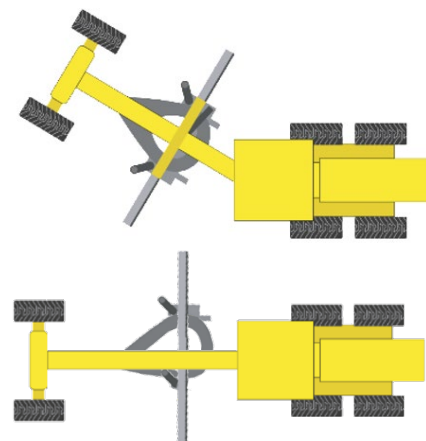
NOTE: BLADE ROTATION



POSSIBLE with following configurations:

- Single Laser
- Sonic Tracer
- Total Station
- Dual Laser
- Dual GNSS
- Single GNSS
- TPS
- Slope sensor
- Rotation sensor

NOTE: ARTICULATION AND CIRCLE SHIFT



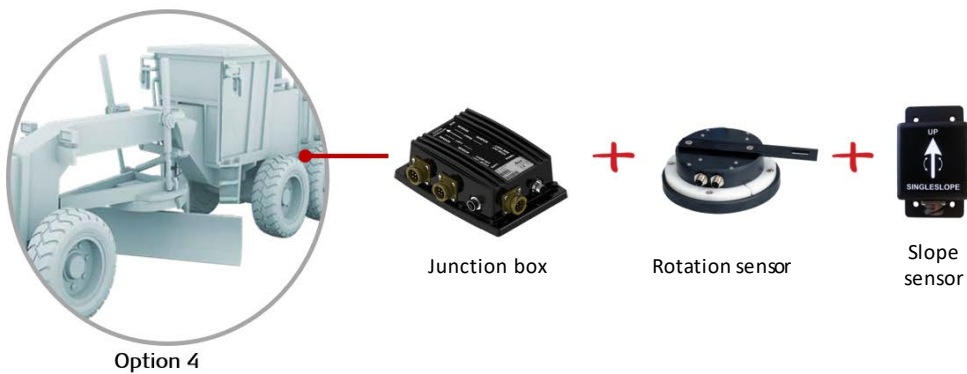
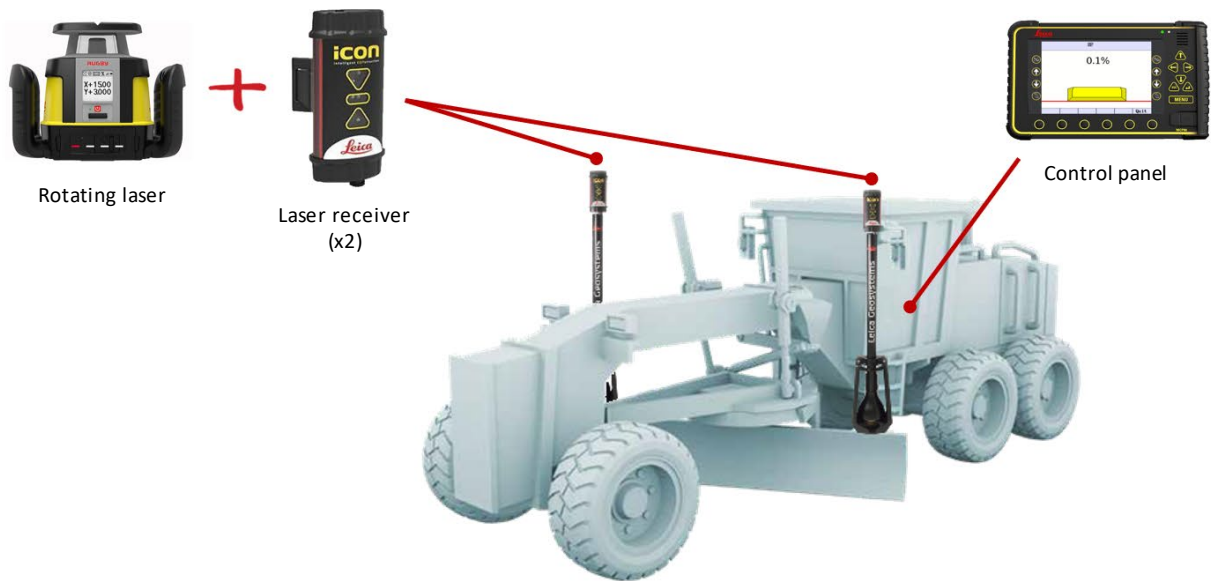
Grading on a slope while articulated or with the circle side shifted **will introduce error** with following configurations:

- Single Laser
- Sonic Tracer
- Single GNSS
- Total Station
- Slope sensor
- Rotation sensor

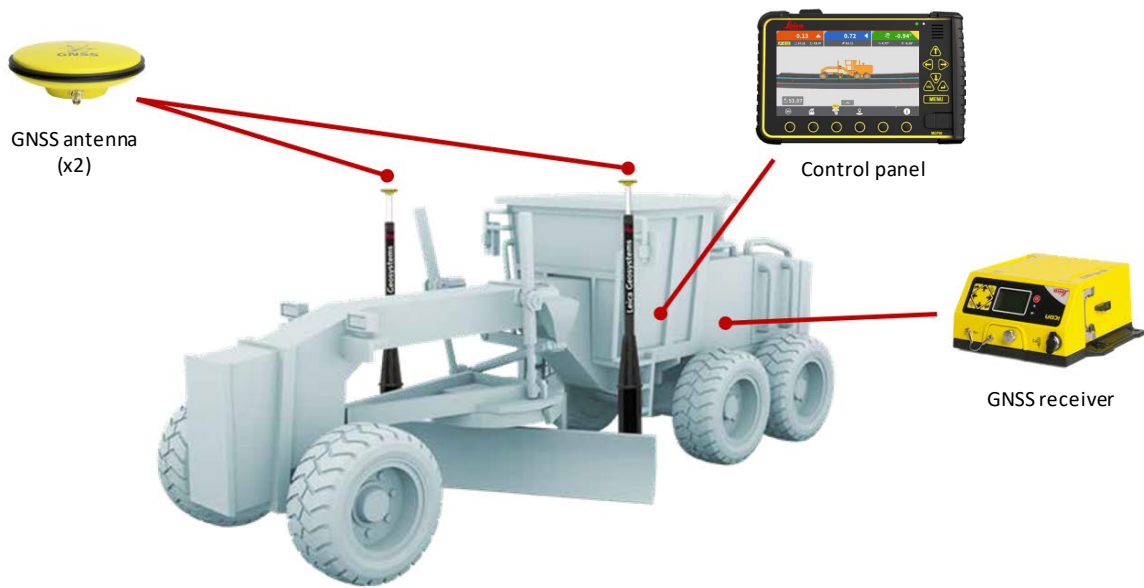
POSSIBLE with following configurations:

- Dual Laser
- Dual GNSS

2D solution (Illustration)



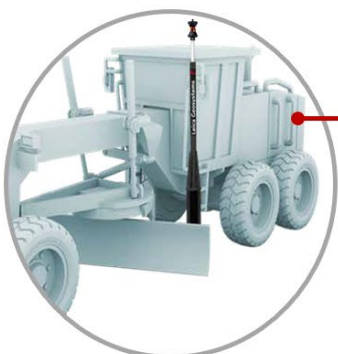
3D solution (Illustration)



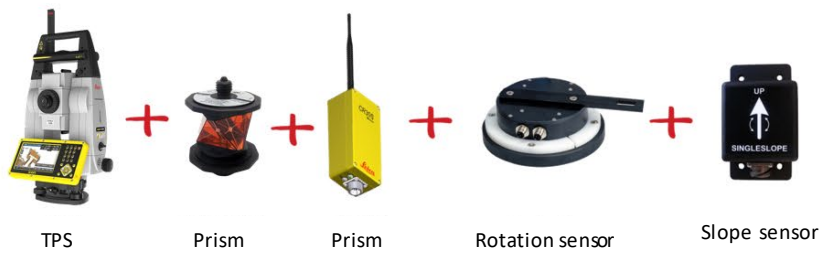
Option 2



Option 3

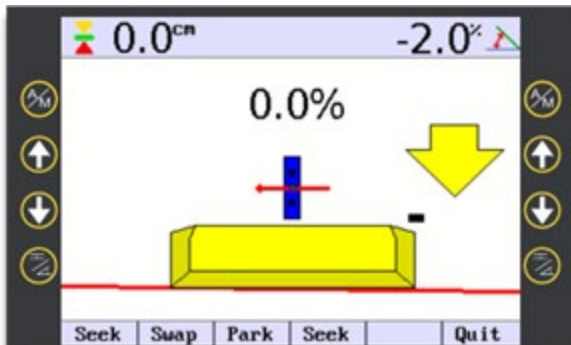


Option 4

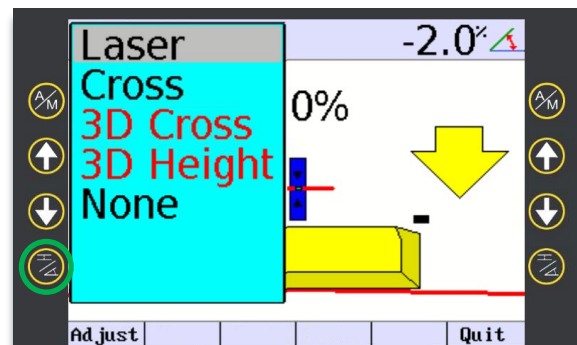


Workflow 02: Define hydraulic performance settings (Gain)

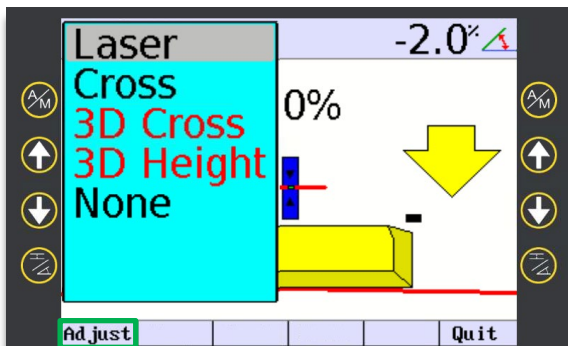
When working with different material types you may need to adjust speed of your machine hydraulics, to better accommodate how the system reacts to different weights of material (Sand compared to heavy organic soil). This is accomplished by adjusting "Gain". A different gain value can be assigned to each sensor. Only small adjustments are recommended. Please note that many other calibration parameters also affect performance.



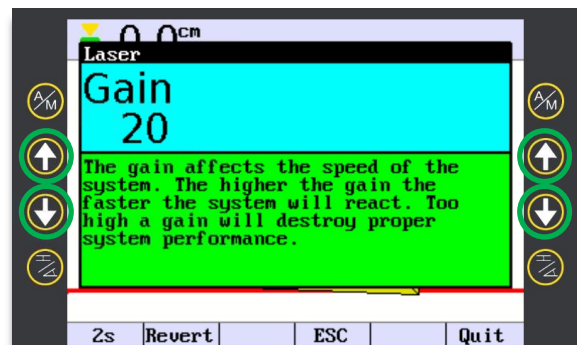
Step 1: Access 2D user interface (See 2D Workflow 01).



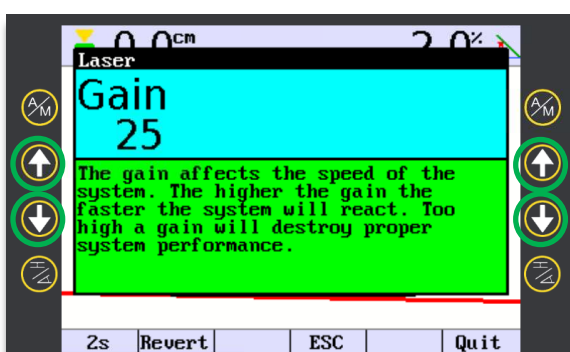
Step 2: Select "Configure" button and highlight desired sensor to adjust.



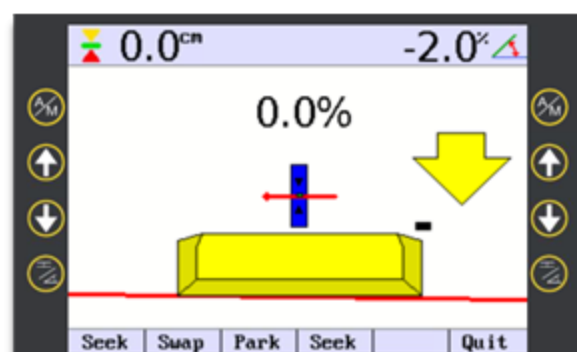
Step 3: Select "Adjust".



Step 4: Use up/down soft or hard keys to adjust gain value until hydraulics perform to satisfaction.



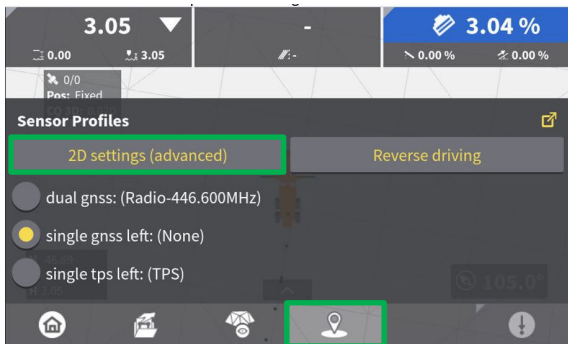
- Tip: Start by changing 10 steps. If too little, then do 10 more. If too much go 5 steps back. Continue this "halving" method until satisfaction.



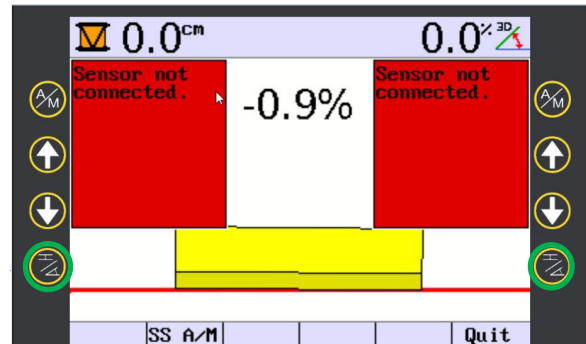
Step 5: Select "Menu" to apply changes and return to run screen.

Workflow 03: Adjust height of an electric mast

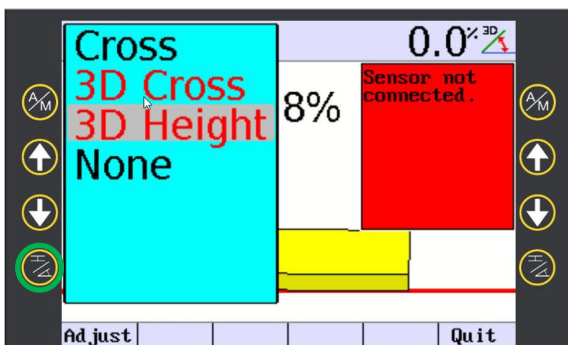
If you operate your machine with an electrical mast in a TPS setup, you may need to adjust mast height. This workflow describes how to adjust the height in the 2D system.



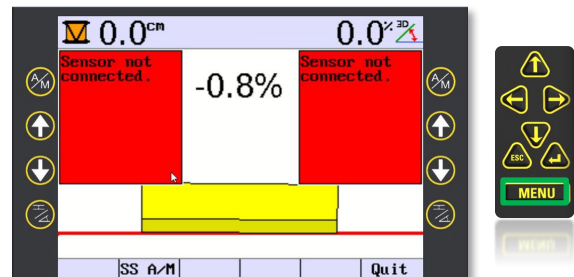
Step 1: Press the positioning icon to enter the 2D settings.



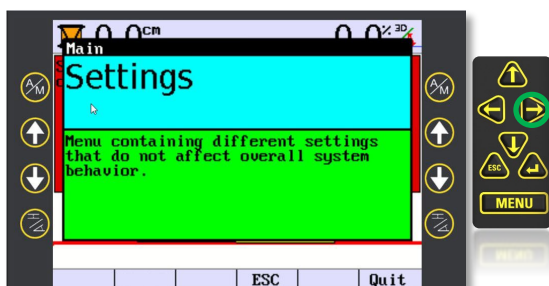
Step 2: Press the configure button on the relevant side to open the sensor menu.



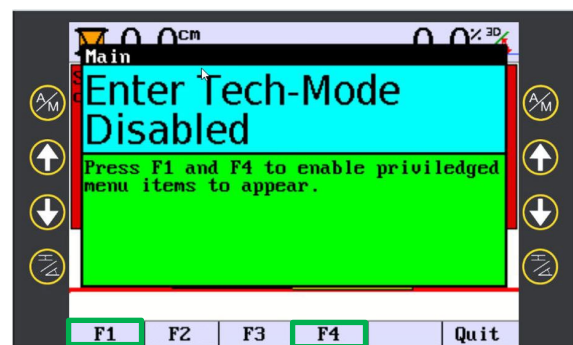
Step 3: Press the arrow buttons to find "Laser" in the sensor menu. Continue to step 10 if laser is available. If laser is not available in the sensor menu list, you need to change to tech-mode. Press the configure button to close the sensor menu.



Step 4: Press the "Menu" button on the hardware to adjust mode.

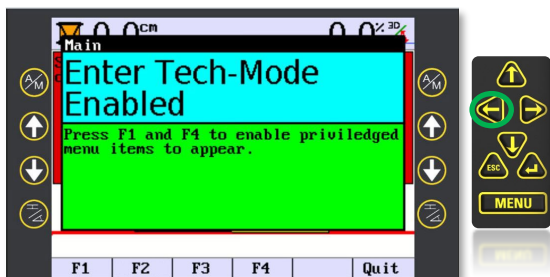


Step 5: Press the right button on the hardware until you find "Tech-Mode".



Step 6: Press the F1 and F4 buttons on the hardware simultaneously to switch the tech-mode from "Disabled" to "Enabled".

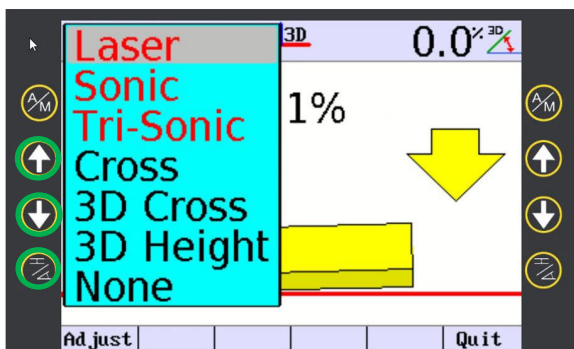
Workflow 03: Adjust the height of an electric mast (continued)



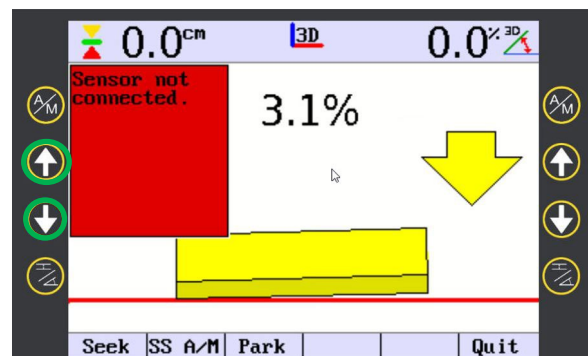
Step 7: When tech-mode is enabled press the left button on the hardware.



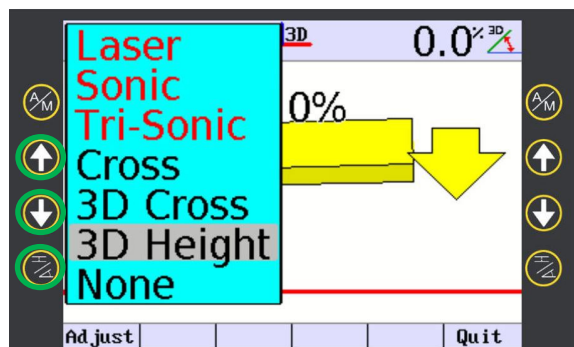
Step 8: Press the "ESC" button to exit to the CB14 run screen. Press the configure button.



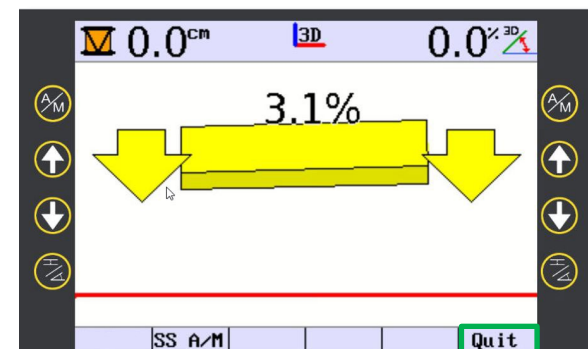
Step 9: Use the arrow keys to select "Laser". Press the configure button to exit the sensor menu.



Step 10: Use the arrow keys to move the mast up or down.

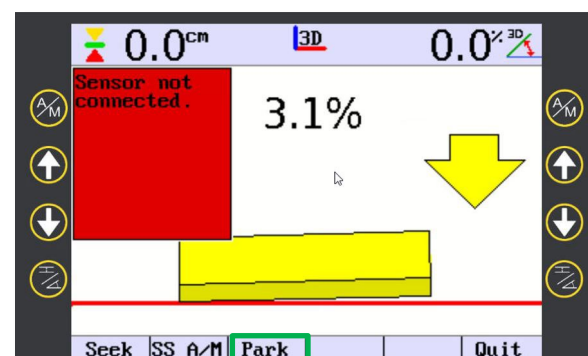


Step 11: Press the configure button to reopen the sensor menu and select "3D Height" with the arrow keys. Press the configure button to exit the menu.



Step 12: Press "Quit" to exit to the MC1 run screen.

Step 13: When you are done working with the adjusted mast repeat steps 1-10 to reset mast height. Press "Park" in Step 10.



Your 2D solution

Workflows in this chapter focus on your 2D machine control solution.



2D solution content:

i 2D settings

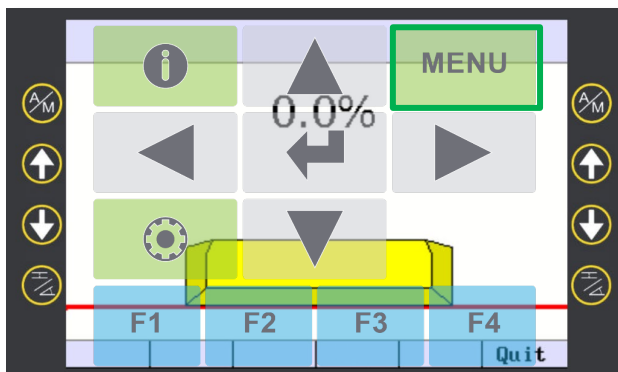
- **Workflow 01:** Switch from 3D to 2D mode
- **Workflow 02:** Operate your machine with "cross slope" only
- **Workflow 03:** Sonic Tracer Considerations
- **Workflow 04:** Operate your machine with "Sonic tracer"
- **Workflow 05:** Laser setup considerations
- **Workflow 06:** Set up a laser to create dual sloping surfaces
- **Workflow 07:** Operate your machine with laser receiver + cross slope
- **Workflow 08:** Operate your machine with "dual" laser receivers

i 2D settings

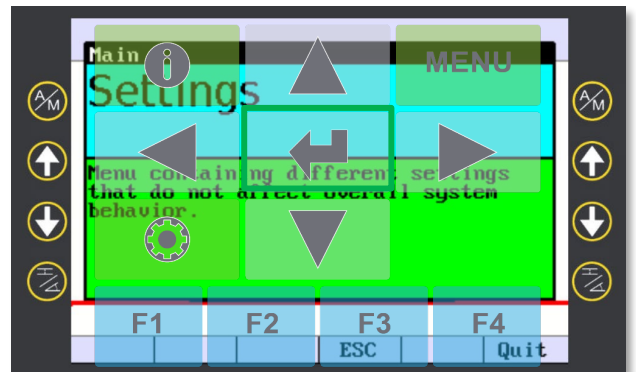
This section outlines available options in the settings menu.

The menu is divided into 9 categories:

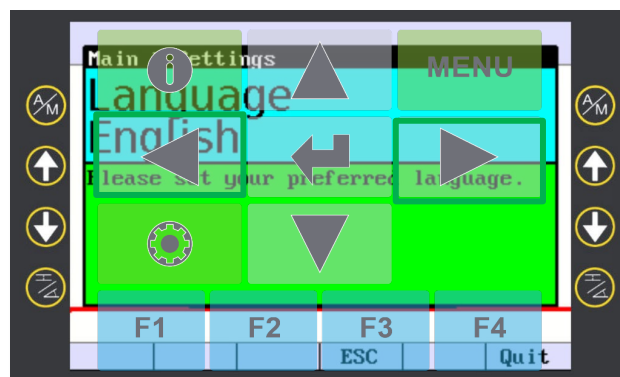
- Language
- Elevation offset increment
- Beep volume
- Diode light
- Info-screen
- LED angle step
- LED distance step
- Distance unit
- Angle unit.



Press "Menu" to enter settings the 2D settings.



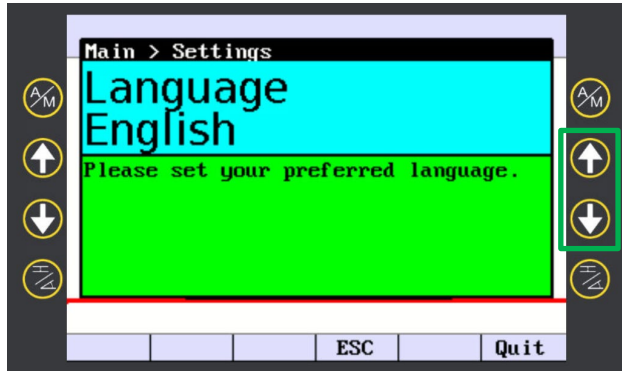
Press "Enter" to access the 9 setting categories.



Press the arrow keys to move through the 9 setting categories.

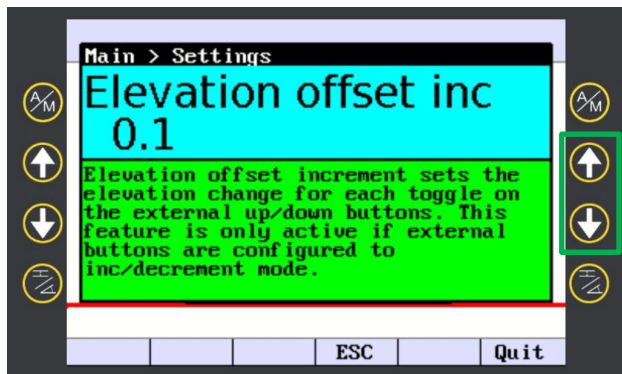
i 2D settings (continued)

Language



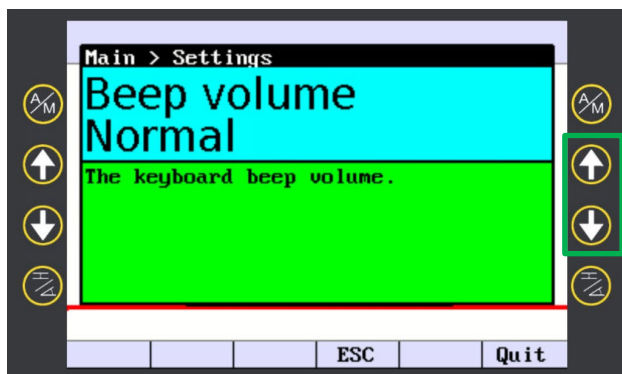
Navigate through the language options using the up/down arrows.

Elevation offset increment



Use the up/down arrows to increase/decrease elevation offset.

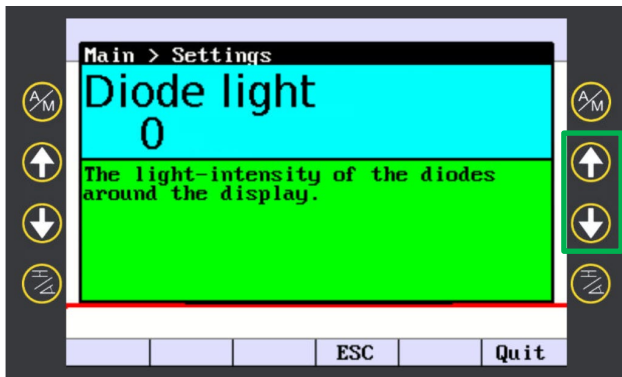
Beep volume



Use the up/down arrows to adjust beep volume.

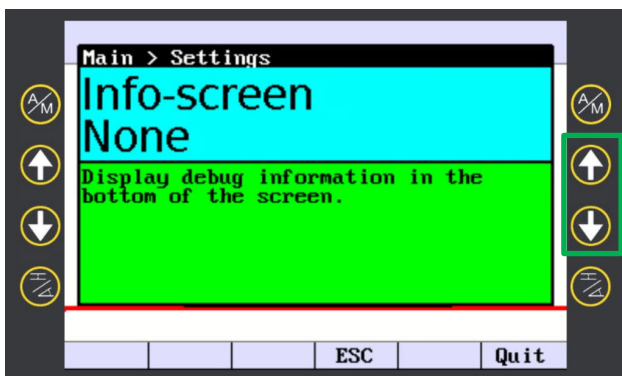
i 2D settings (continued)

Diode light



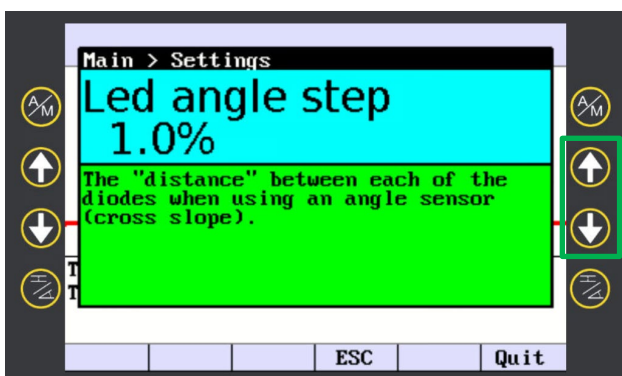
Use the up/down arrows to adjust the light intensity of the diodes around the display.

Info-screen



Use the up/down arrows to adjust info screen debug information (none, hydraulic, sensor, 3D, runtime).

LED angle step



Use the up/down arrows to adjust distance between diodes when using an angle sensor.

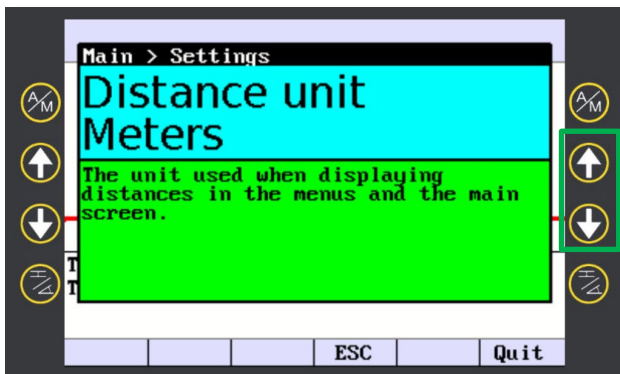
i 2D settings (continued)

LED distance step



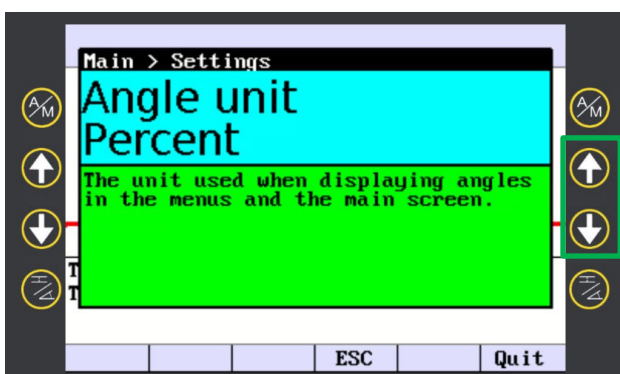
Use the up/down arrows to adjust distance between diodes when using an elevation sensor.

Distance unit



Use up/down arrows to adjust distance units in menus and main screen (meters, inches, feet).

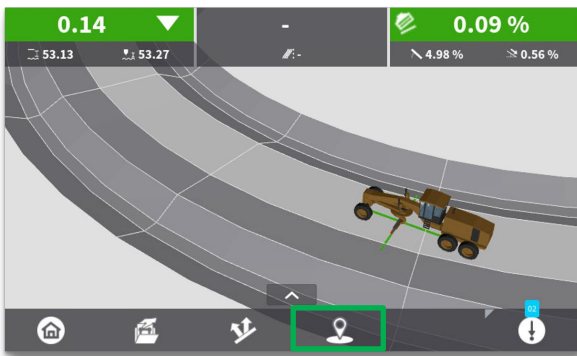
Angle unit



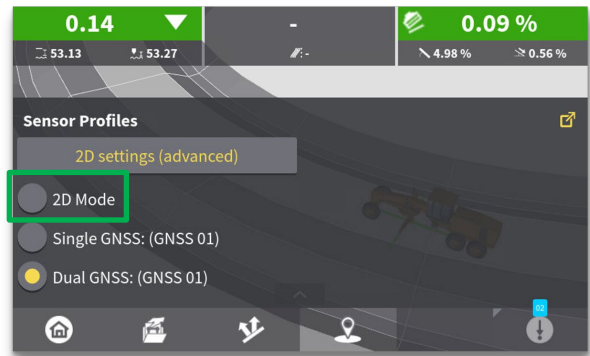
Use up/down arrows to adjust angle units in menus and main screen (percent, permille, degrees).

Workflow 01: Switch from 3D to 2D mode

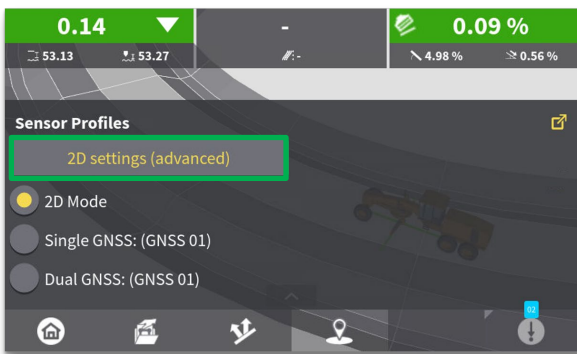
This workflow shows you how to switch from 3D to 2D work mode in MC1.



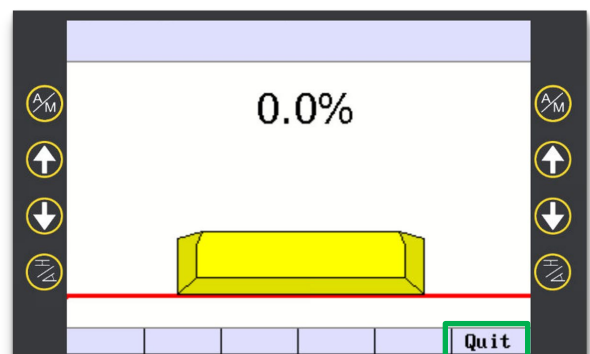
Step 1: Press "Positioning" menu.



Step 2: Press "2D mode" to enter 2D mode.



Step 3: Press "2D settings (advanced)" to access the CB14/2D run screen.

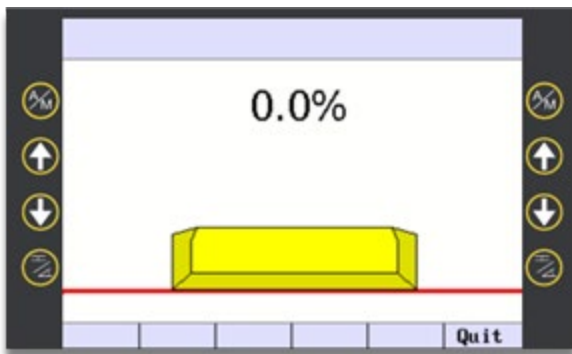


Step 4: Select sensors to use, and start working in 2D mode.

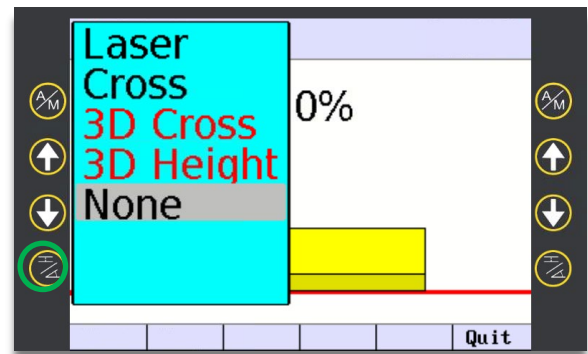
When needed, press "Quit" (panel hardware button) to return to the MC1 run screen. Remember to re-select a 3D sensor profile to return to 3D mode in the MC1 run screen.

Workflow 02: Operate your machine with "cross slope" only

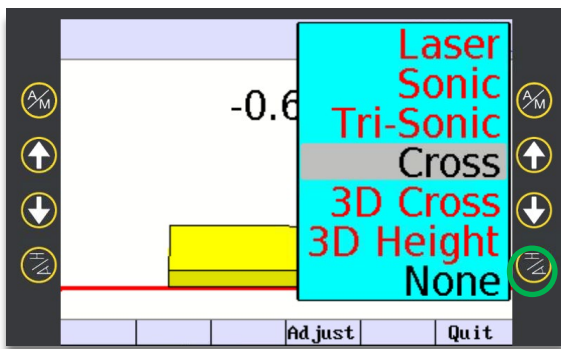
With only a cross slope sensor, and if hydraulics are available, cross slope automatics is used with this configuration. Manually adjusting height for elevation is required.



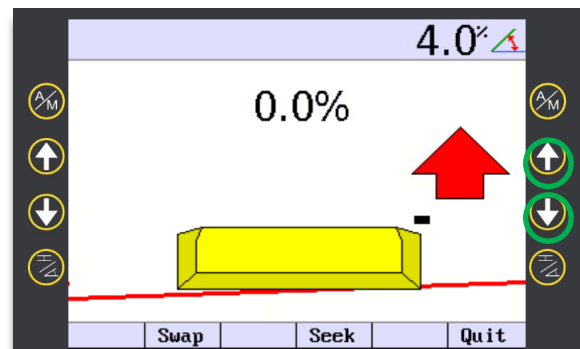
Step 1: Access 2D user interface (See Workflow 01).



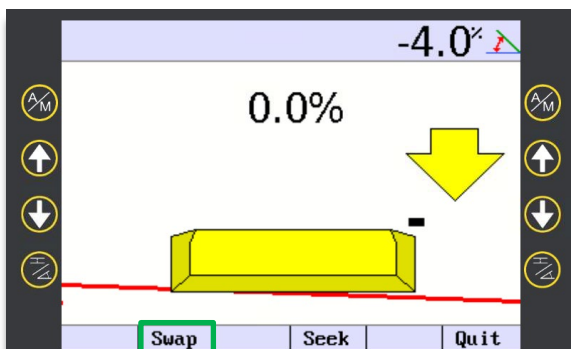
Step 2: Select "left side" configure softkey and use up/down arrows to select "None" for the Left tip configuration.



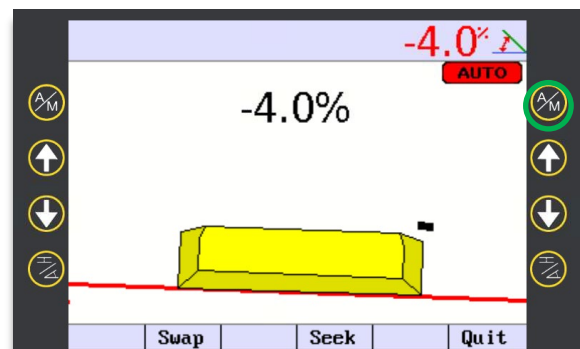
Step 3: Select "right side" configure softkey and use up/down arrows (Softkey or Keypad) to select "Cross".



Step 4: Use right side "up/down" softkeys, to dial in desired slope. "Seek" can be used to read the slope of the blade. Long Press "Seek" to bench the cross slope value from existing surface.



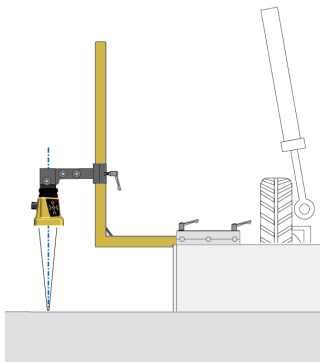
Step 5: An arrow will indicate the direction the blade needs to move to match the slope. Select the "Swap" hard key to change slope direction.



Step 6: Select A/M to engage automatic hydraulic functions (If equipped) and the blade will move to the desired slope.

Workflow 03: Sonic tracer considerations

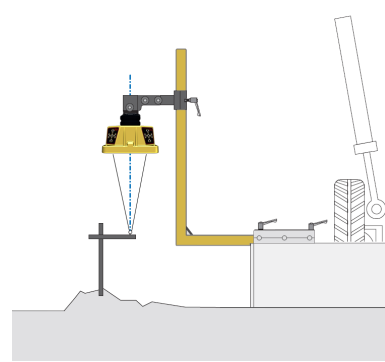
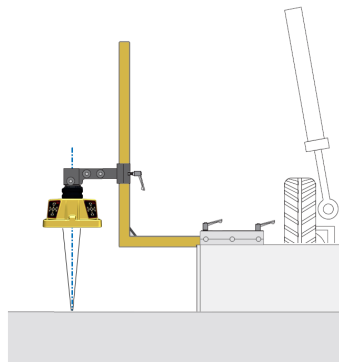
Step 1: Mount the Tri-Sonic at appropriate height, for maximum performance, according to selected reference surface (See illustrations below for sensing ranges).



Ground sensing range:

Sensing range: 20-200 cm (8-79 inch).

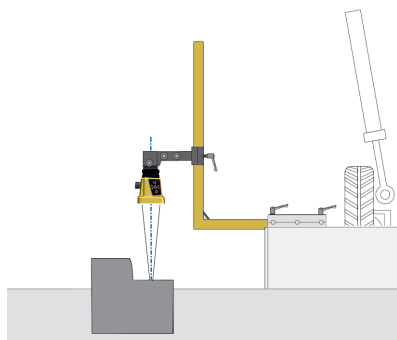
Best performance: 60 cm (24 inch).



Stringline sensing range:

Sensing range: 40-70 cm (16-28 inch).

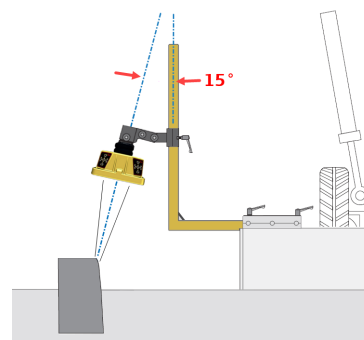
Best performance: 60 cm (24 inch).



Curb gutter sensing range:

Sensing range: 40-70 cm (16-28 inch).

Best performance: 60 cm (24 inch).



Curb edge sensing range:

Sensing range: 40-70 cm (16-28 inch).

Best performance: 60 cm (24 inch).

Curb edge sensor angle:

Best performance: 15°

NOTES:

The sensor has two different warnings that will be displayed for the user when the sensor is not within sensing range:

Window error

The sensor's measuring window is by default an area/window of ± 10 cm around the operating point. If measurements are outside this window, then "Window error" will be displayed. This function will help the operator to keep the sensor on the desired target, and eliminate the risk of measuring to a wrong surface

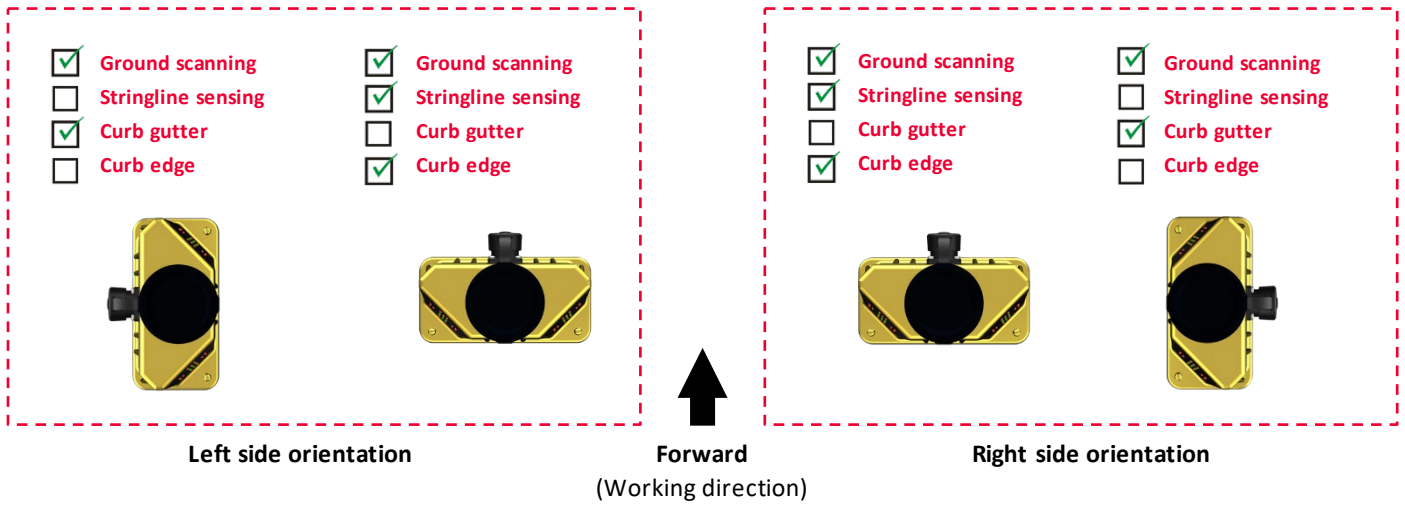
Physical range error

When the sensor is getting too close to, or too far from, the physical object it measures distance to, then "Physical range error" will be displayed. This means that when the distance between sensor and measured object is outside the "sensing range" (as indicated in above illustrations), then the operator will be alerted. This function will help the operator to stay within the recommended working area for the sensor.

See **Step 2** on next page for information on how to orient the sensor.

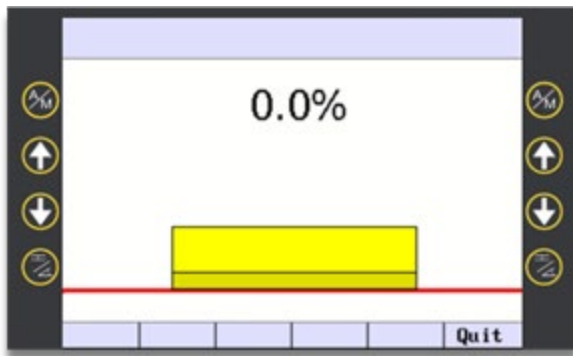
Workflow 03: Sonic tracer considerations (continued)

Step 2: Orient the Tri-Sonic perpendicular or parallel to machine working direction, depending on the reference being used (The connector should always face away from the operator, to the side or forward, to allow LED indicators to be visible from cab).

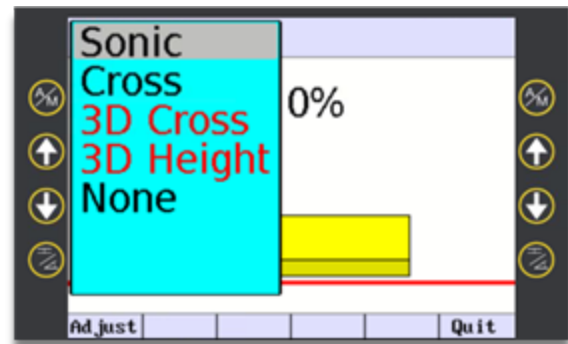


Workflow 04: Operate your machine with "Sonic tracer"

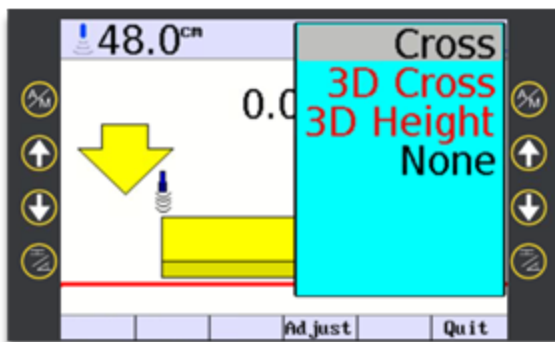
Sonic tracers are useful in grading when you need to match an existing surface, curb or have a string line for elevation control.



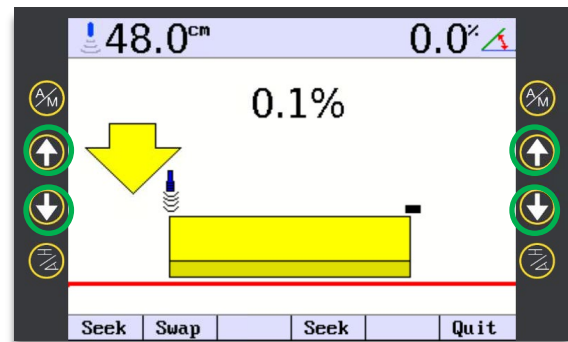
Step 1: Access 2D user interface (See Workflow 01)



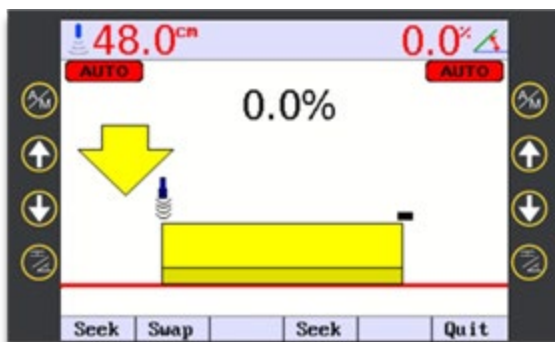
Step 2: Select "left side" configure softkey and use up/down arrows (Softkey or Keypad) to select "Sonic". Press "Config" or "Enter".



Step 3: Select "right side" configure softkey and use up/down arrows (Softkey or Keypad) to select "Cross". Press "Config" or "Enter".



Step 4: Use softkey arrows to set desired height and cross slope. The system will guide you to the correct grade.



Step 5: Select A/M to engage automatic hydraulic functions (If equipped) and the blade will move to the desired height and slope.

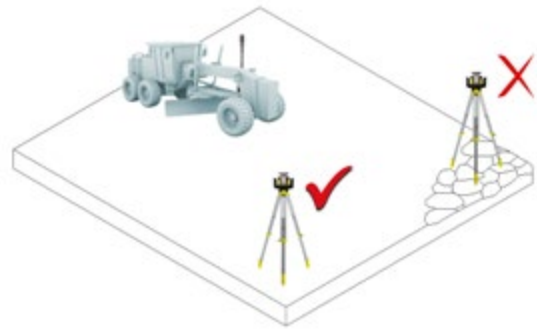
Workflow 05: Laser setup considerations

Set up a machine control laser for optimum coverage of the job site. It must be out of traffic and any obstructions. Position laser and tripod at a height equal to the laser receiver mounted on your machine, when it is on grade. Adjust alignment of your laser to the site as needed.



Step 1: Choose a good location for your laser.

- No obstructions that could block or reflect the laser.



- Stable ground, so the tripod won't shift or settle (Ground Vibration can affect operation of the laser).



- Up-wind, in very dusty environment, so dirt is blown "away" from your laser.



Step 2: Adjust height of your laser beacon and laser sensor:

- Height should, if possible, be above cab (This prevents cab, or roll-over structure, from blocking your laser).

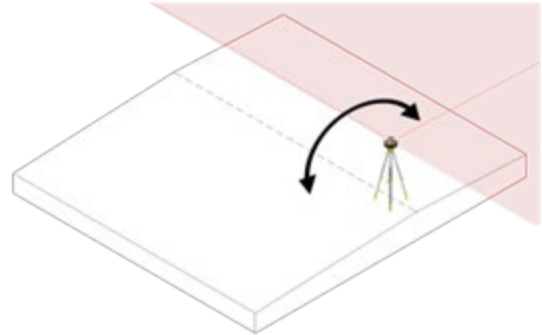
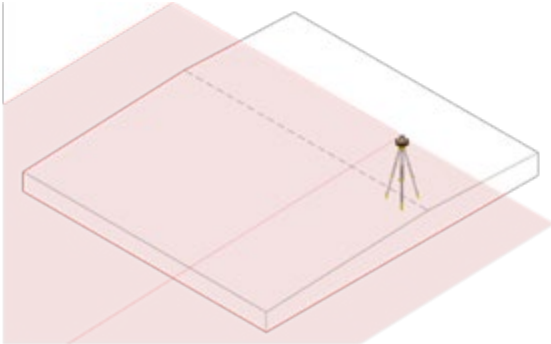


Step 3: Check tripod, then attach your laser.

- Make sure all tripod screws, bolts and nuts are tight.
- Place laser on tripod and tighten screw on underside to secure it to the laser tripod.
- If your tripod has chains, those chains should be slightly loose to allow for thermal expansion during the day.
- Secure your tripod in very windy conditions.

Workflow 06: Setup a laser to create dual sloping surfaces

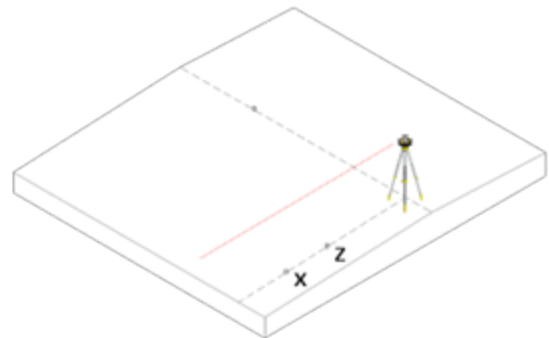
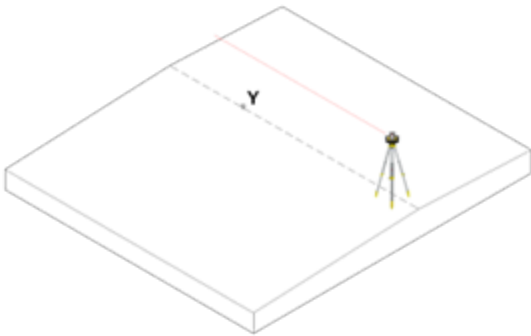
Dual Sloping surfaces are defined by a master alignment (Y) and a cross-slope on either side (X). Optionally an additional hub can be set for height reference (Z) along the X-axis.



Step 1: Choose optimum laser location:

- The location should allow you greatest possible working range on your site.

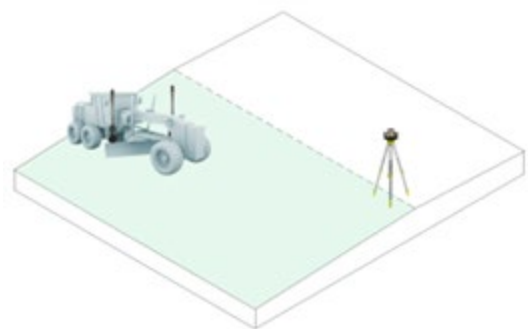
- If the slope is mirrored, and if grading will be done on both sides, it is helpful to place your laser on the crown (This way the grade can be swapped on the laser without additional setup).



Step 2: If the grade has a dual slope, have the surveyor set hubs along X and Y axis.

- Y axis defines CL and machine long slope (Align your laser precisely with this CL).

- One hub along X axis will be used for "height benchmark" the other for cross slope (Adjust laser based on this X-slope).

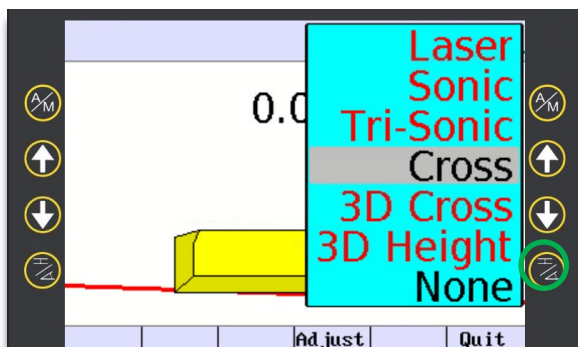


- X-axis hubs can be used to establish cross slope manually, as pictured here. If an X-slope sensor is installed, slope can also be dialed in to match the laser.

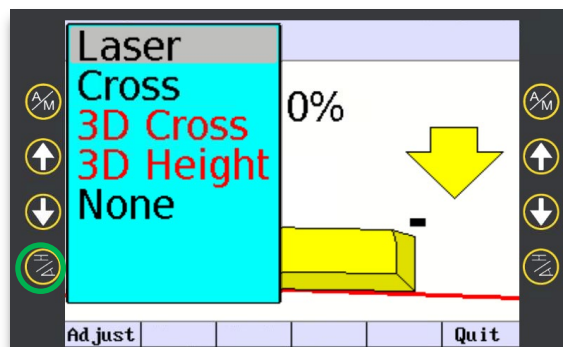
Step 3: Place the blade at desired working height. Adjust the laser receiver on your machine to catch the laser strike, at the center. Now, grade on the slope that matches the laser.

Workflow 07: Operate your machine with laser receiver + cross slope

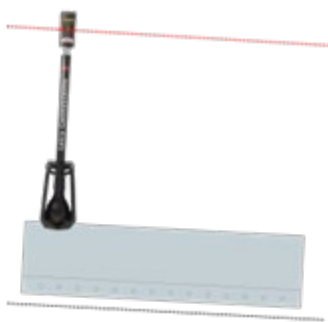
Single Laser is an economic option, but you must be aware of the travel direction when grading. Travel diagonally across a slope will provide incorrect guidance with single laser. Cross slope values must match entered value in laser.



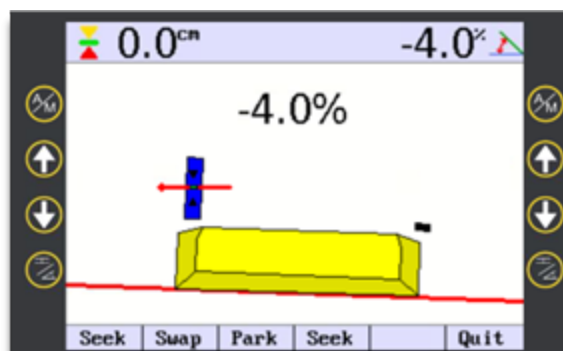
Step 1: Press "right side" configure softkey, and select "Cross".



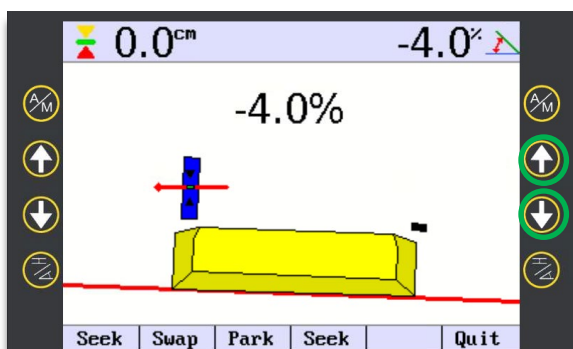
Step 2: Press "left side" configure softkey, and select "Laser".



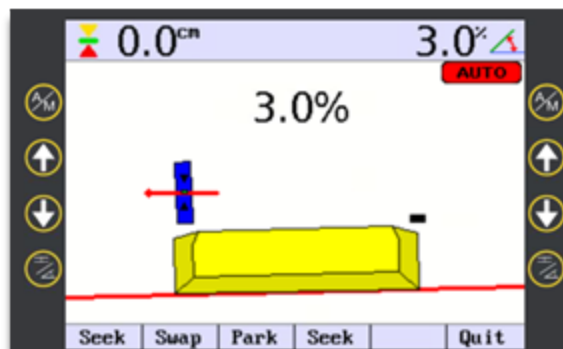
Step 3: Place blade on desired cross slope. Move laser receiver until green "on grade" indicators show. Alternatively, if using power masts, use "Seek" softkey to locate beam.



- When laser receiver is within laser strike, a red horizontal arrow appears on screen.



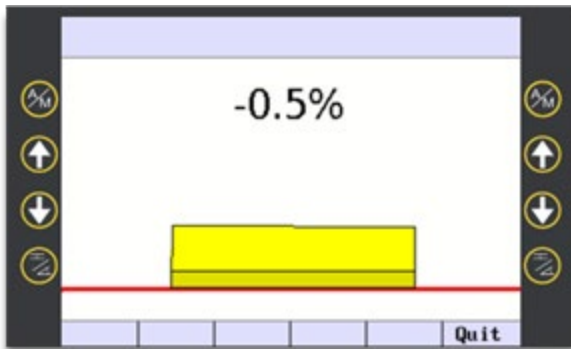
Step 4: Use "up/down" softkeys to dial in desired cross slope matching laser value. An arrow indicates the direction the cross slope-controlled tip should move to be on grade.



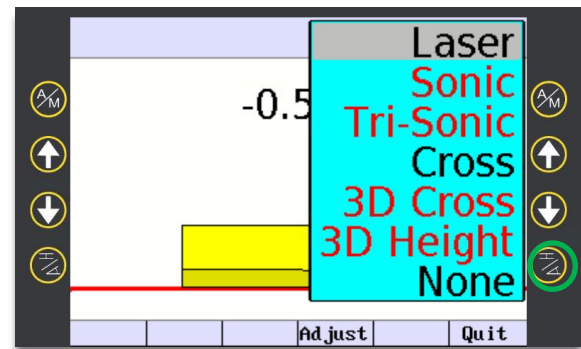
Step 5: Select A/M softkey on cross slope side to enable automatics. When "on grade", the arrows will NOT appear, and centre line of laser catcher illuminates green. Auto switch function has 4 options, selectable by tech.

Workflow 08: Operate your machine with "dual" laser receivers

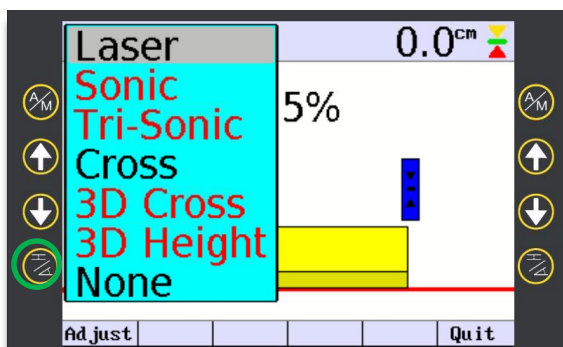
When working with dual laser you can run your machine in any direction, regardless of slope. Cross slope of blade will be determined by laser cross slope. With dual laser you are free to rotate the blade if necessary. Desired cross slope must match the slope that is dialled into the laser.



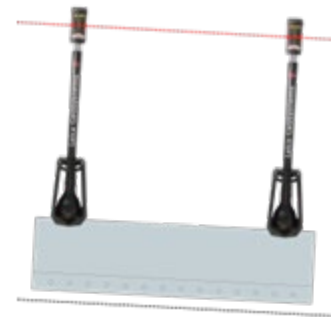
Step 1: Access 2D user interface (See Workflow 01).



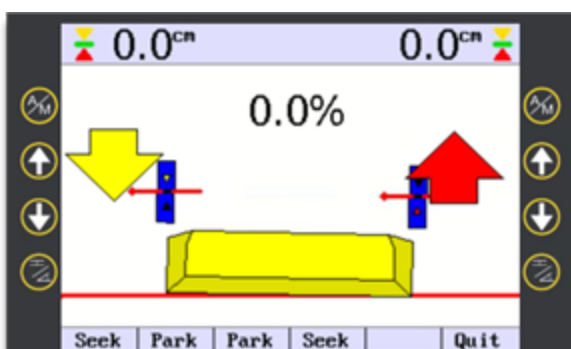
Step 2: Press "right side" configure softkey, and use up/down arrows (Softkey or Keypad) to select "Laser".



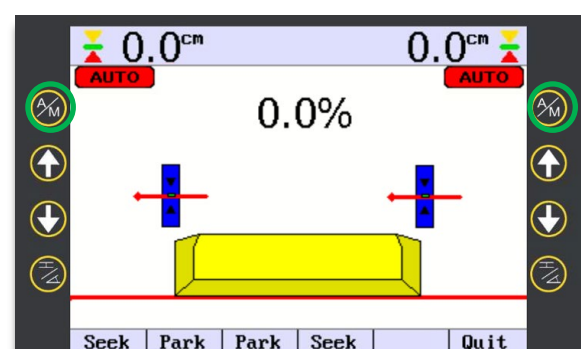
Step 3: Select "left side" configure softkey, and use up/down arrows (Softkey or Keypad) to select "Laser".



Step 4: Place blade on desired cross slope. Move laser receiver until green "on grade" indicators show. Alternatively, if using power masts, use "Seek" softkey to locate beam.



- When laser receivers are within laser strike a red horizontal arrow appears on screen. Other arrows indicate the direction each tip should move to be on grade.



Step 5: Press A/M softkey, on either sides, to enable "Automatic". When "on grade" the arrows will not appear, and centre line of laser catcher illuminates green. Auto switch function has 4 options, selectable by tech.

Workflow 09: Configure sensor position without the MJB130x junction box

This workflow is only relevant for systems that does not have an MJB130X junction box. If you do have an MJB130x junction box, then the sensors must be set to left. The workflow describes how to program 2D sensors for left or right-side mounting for a single or dual sensor setup. It is temporarily necessary to go through these steps if you do not have the MJB130x junction box installed in the system.

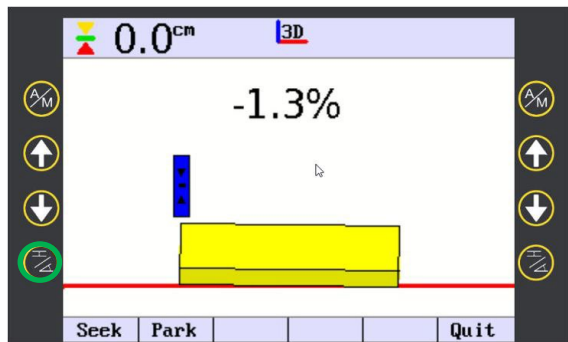
Supported sensors (minimum software requirement: CB14 on MCP80 v. 2.91 and CB14 on SJB22 v. 4.2.0):

- **MLS720** laser receiver (serial numbers after 20209488 / 06.01.2020).
- **MLS820** laser receiver.
- **MUS1400** tri-sonic sensor.
- **MPM700** electric mast (serial numbers after 30101870 / 14.11.2022).

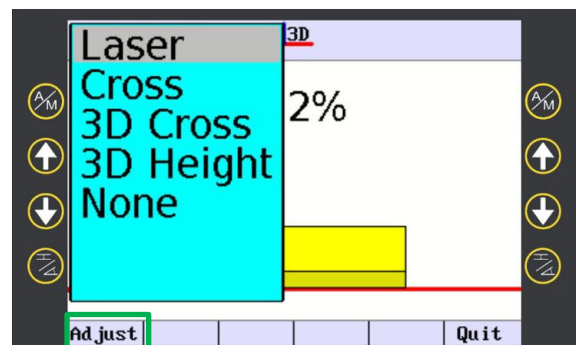
Older sensors can be used only as a left sensor alone or with a new sensor as the right.

NOTES:

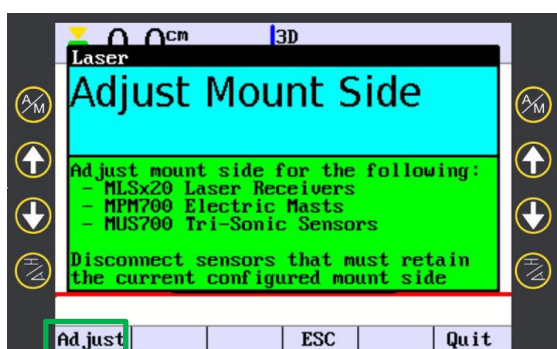
- Disconnect all sensors that should maintain current mount side configuration.
- Only connect the sensor you want to reconfigure.
- All sensors are by default left side configured.



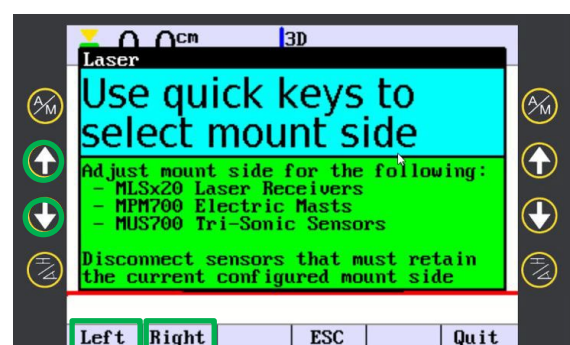
Step 1: Access 2D user interface. Press the left side configure button.



Step 2: Select "Laser" and press "Adjust" to enter the "Adjust Mount Side" menu.

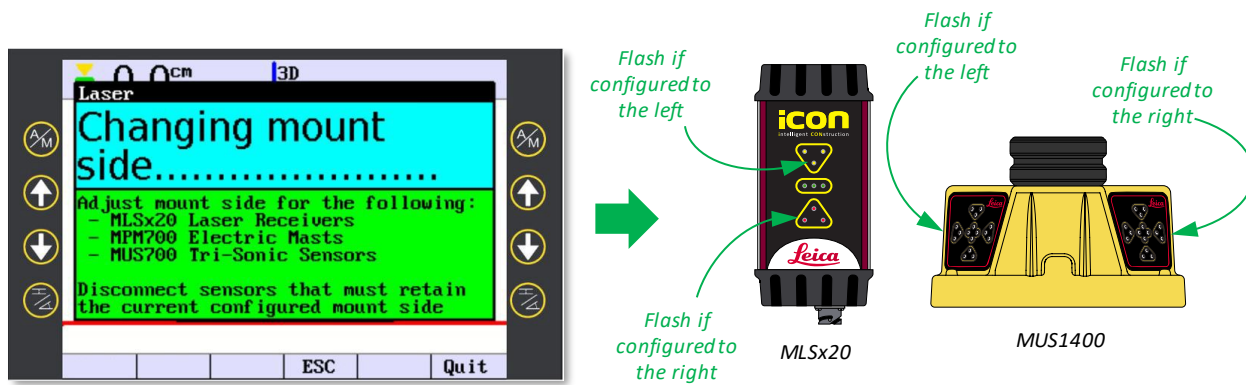


Step 3: Press "Adjust".



Step 4: Read through the instructions. Press "Left" or "Right" to set mount side for connected sensor.

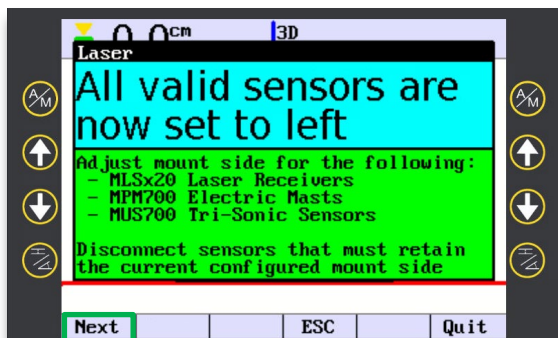
Workflow 09: Configure sensor position without the MJB130x junction box (Continued)



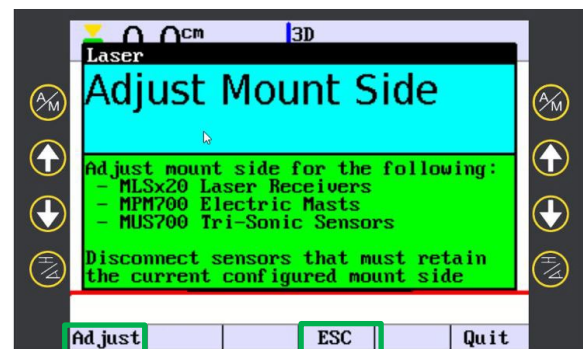
Step 5: Verify mount side configuration.

During power-up and side configuration:

- MLSx20 sensor: The top LED will flash for two seconds if mount side is configured to the left. The bottom LED will flash for two seconds if mount side is configured to the right.
- MUS1400 sensor: The left LED will flash two seconds if mount side is configured to the left. The right LED will flash for two seconds if mount side is configured to the right.
- MPM700 mast: No flash indication for mount side configuration.



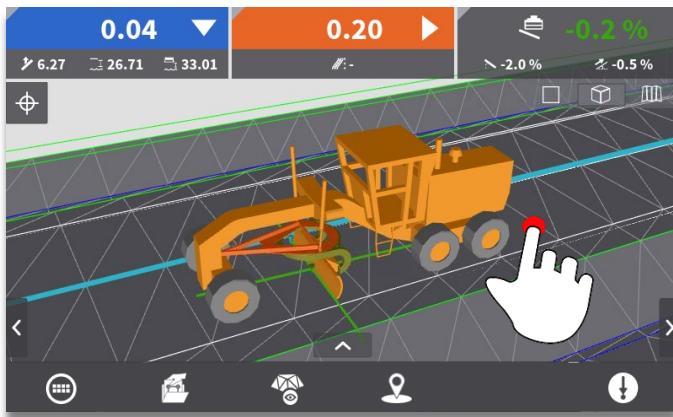
Step 6: Press "Next" to continue configuring.



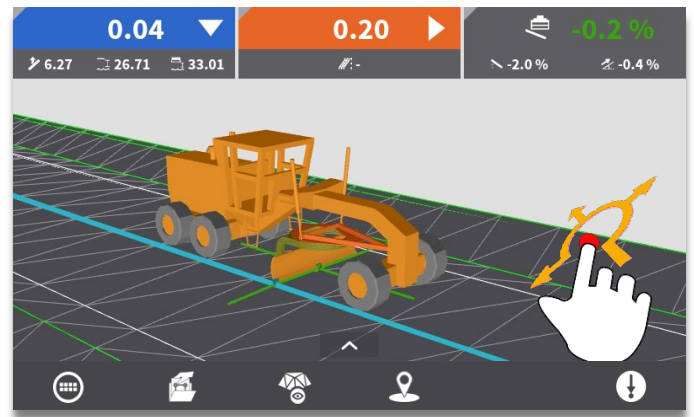
Step 7: Press "Adjust" to configure right-side sensors for a dual setup. If you only need a left-side configuration, press "ESC" to exit to run screen.

i Touch navigation

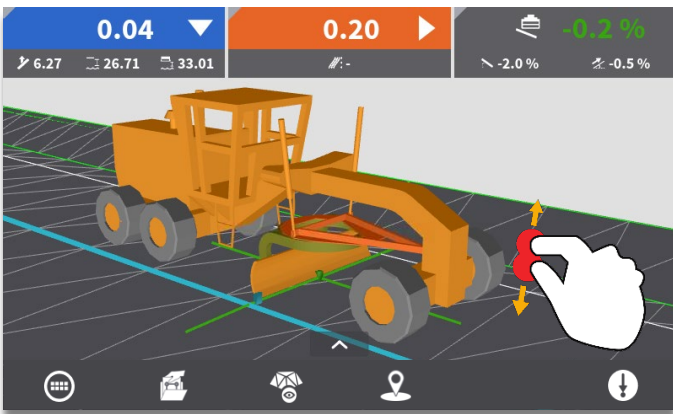
The MCP80 panel display allows multi-touch navigation of run screens.



Single finger tap: Show navigation controls



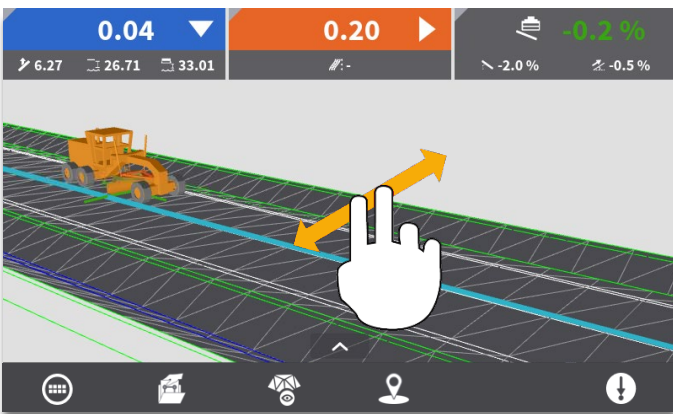
Single finger press and drag: Rotate view



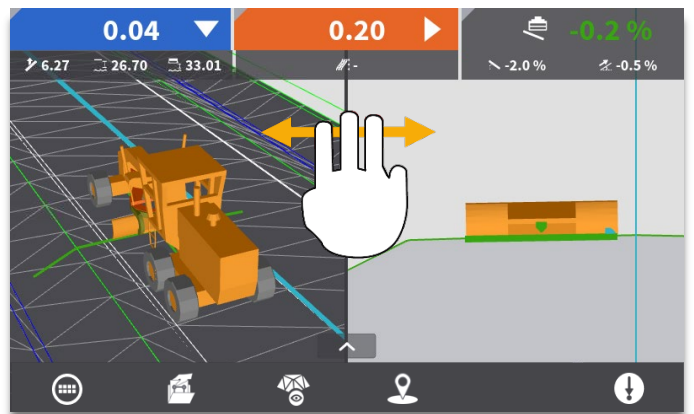
Pinch close: Zoom in



Pinch open: Zoom out



Two-finger press and drag: Pan

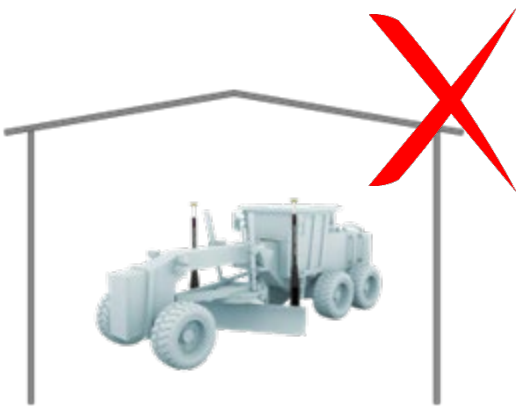


Three-finger press and drag horizontally: Change View

GNSS basics



- When using GNSS, your machine must be within radio range of the local base. Alternatively, if you use an internet base, your machine must be connected via modem.



- GNSS Signal cannot be used indoors or under a canopy of trees.



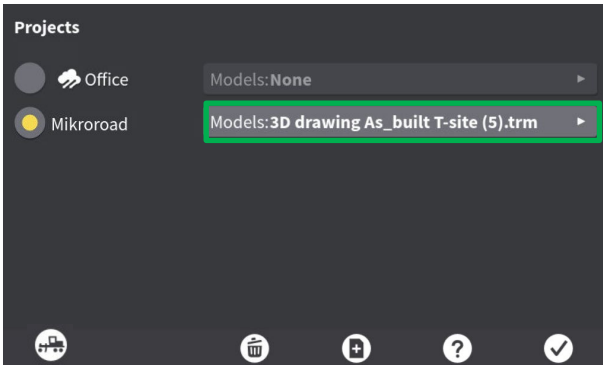
- When operating close to large reflective surfaces (Such as billboards or windows) positioning quality could be affected.



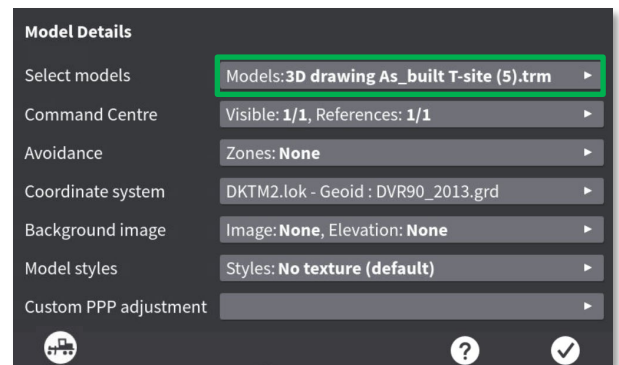
- When operating near "high power" lines, positioning quality could be affected.

Workflow 01: Find your project and models

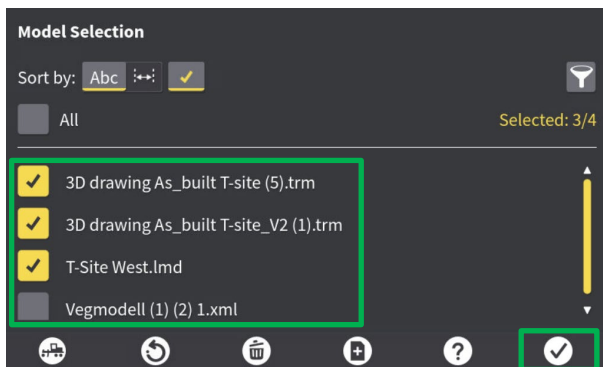
Multiple models can be loaded for a project, and several references can be made available for selection in the command centre. The command centre can be accessed from the run screen, or in "Projects" menu. If you already have all the necessary files loaded for your project, skip ahead to "Step 4".



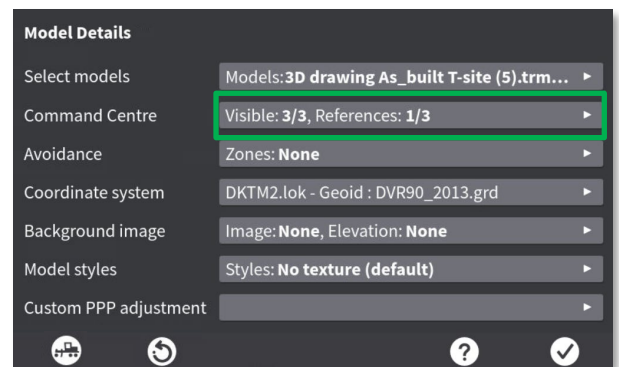
Step 1: Press the menu next to the project you are using, to view model details.



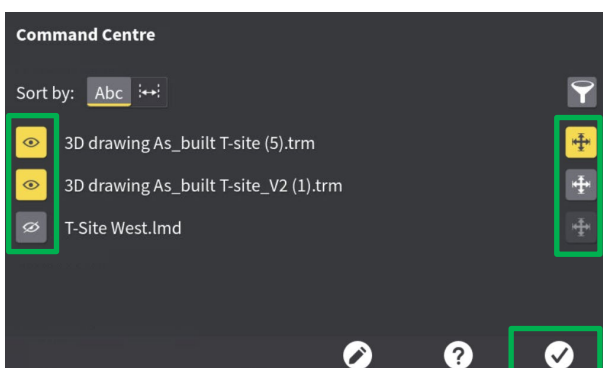
Step 2: Press the "Select models" menu, to access available models.



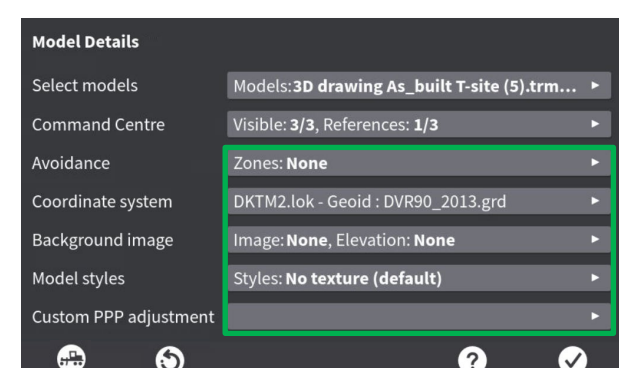
Step 3: Select models to be available in the command centre. Press the tick mark icon (OK) to return to previous menu.



Step 4: Press the "Command centre" menu, to access available models. You can also access the command center from the run screen ([Workflow 02](#))

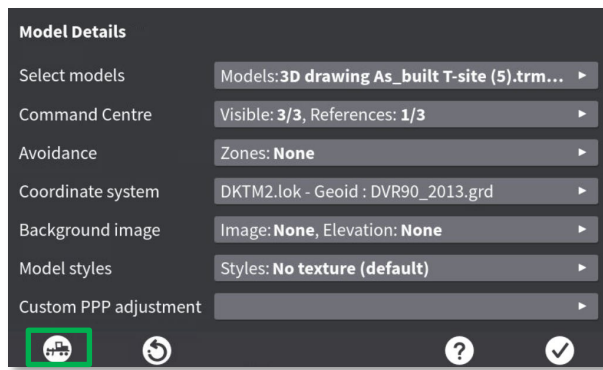


Step 5: Set which references that should be visible and available for selection in the run screen. Press the tick mark icon (OK) to return to previous menu.



Step 6: (Optional) Select Avoidance zones, Coordinate system, Background image, Model styles and Custom PPP adjustment in these menus. Press tick mark icon to apply changes.

Workflow 01: Find your project and models (continued)



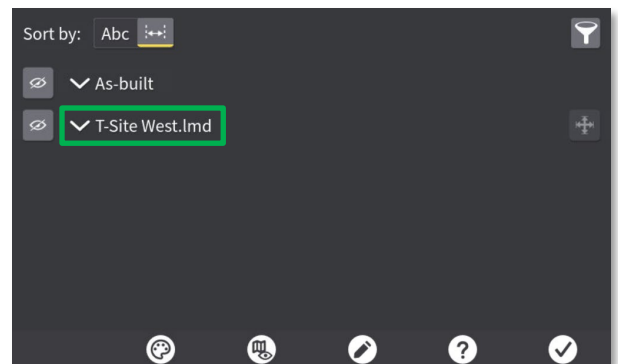
Step 7: Press the grader icon to apply changes and return to run screen.

Workflow 02: Select and use references from run screen

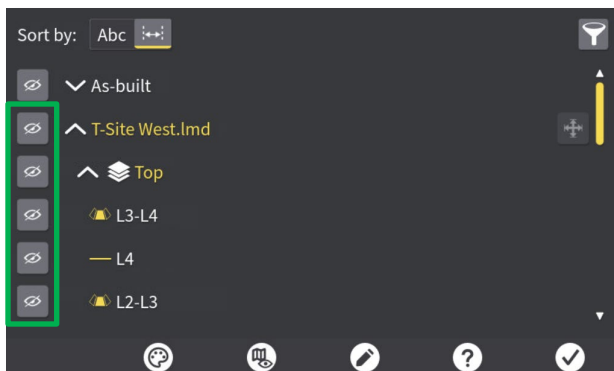
Available models must be loaded in "Select models" menu (See Workflow 01). Once this is done, you can easily switch between models in the run screen. You can make multiple references from multiple models available for selection in the run screen.



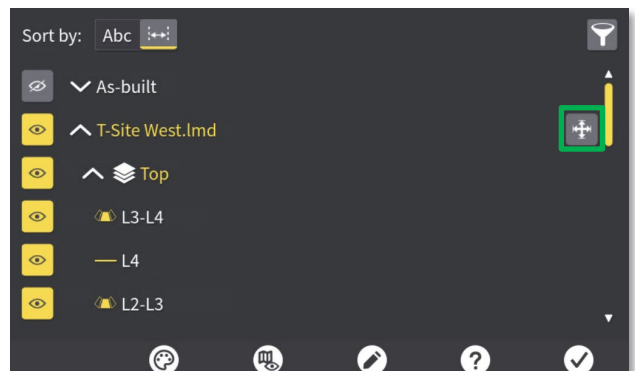
Step 1: Press the "Command centre" menu.



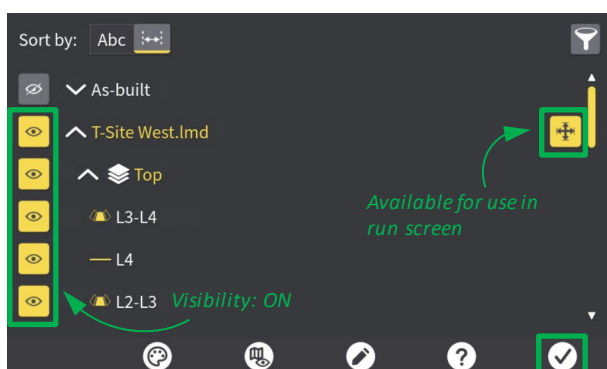
Step 2: Press a model to view the references within. If needed, press the "pencil" icon to access the "Select models" menu, where you can add or remove models in the command centre.



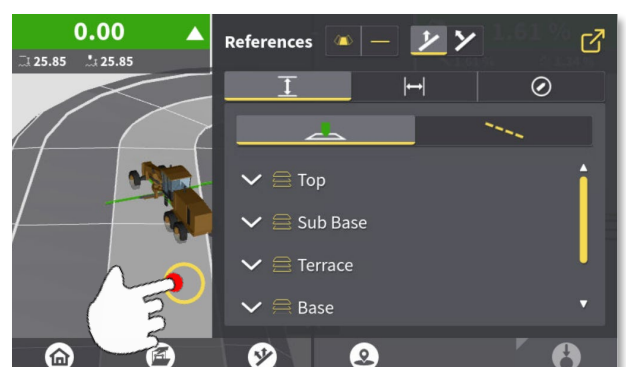
Step 3: Select the references you want to make visible in the run screen. You may need to expand the model further to see all references.



Step 4: Select which references you want to make available for use in the run screen.
NOTE: references cannot be made available for use in the run screen if visibility is turned OFF.

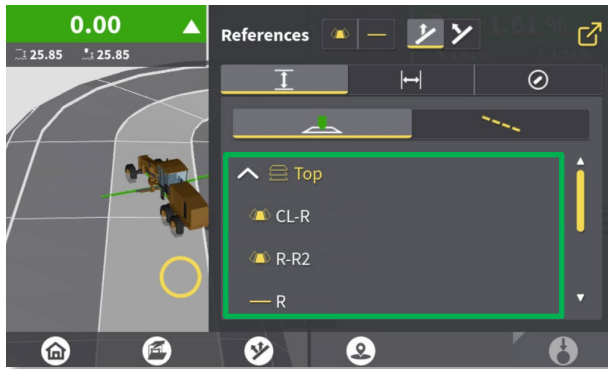


Step 5: Press the tick mark icon (OK) to return to the run screen.

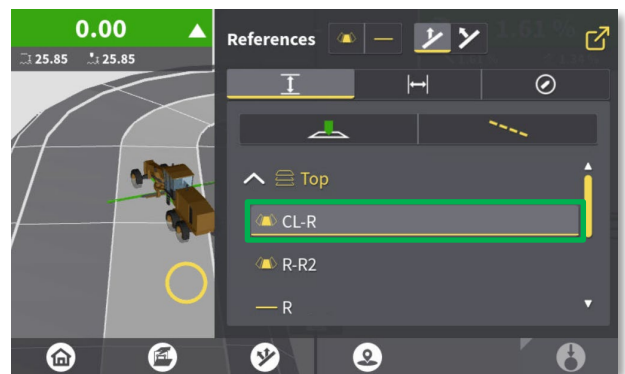


Step 6: Press and hold on the model to see the "References" menu. In this case the height reference tab is selected. Press one of the other tabs if needed.

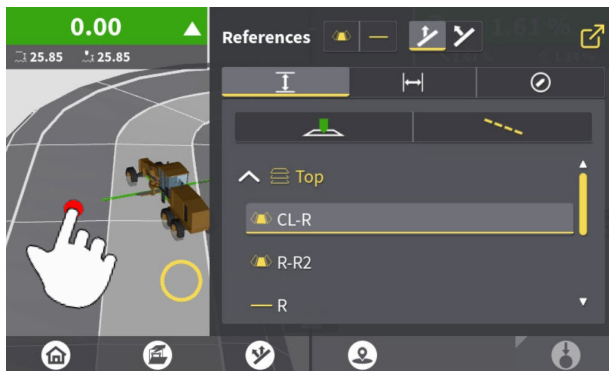
Workflow 02: Select and use references from run screen (continued)



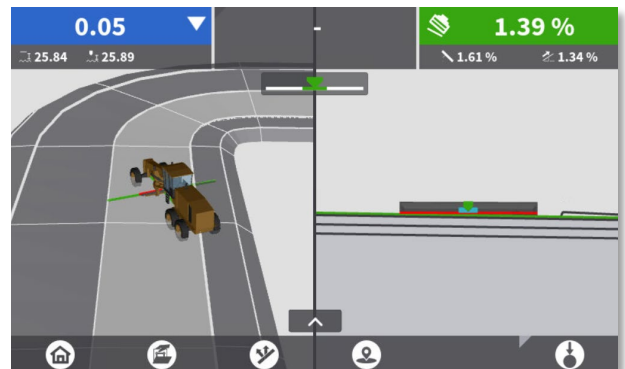
Step 7: Expand the model containing the references you want to work with.



Step 8: Select the desired height reference ("CL-R" shown here).



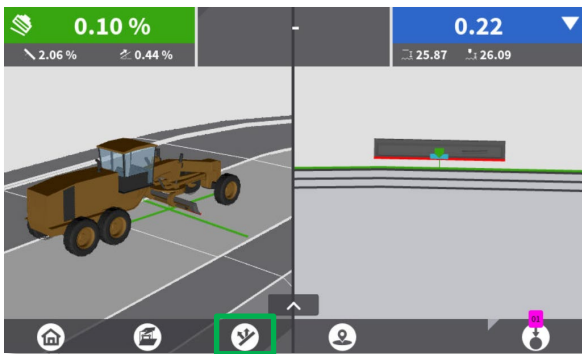
Step 9: Tap anywhere in the plan view to exit the "References" menu.



- The selected reference will be represented by a bold green line. Cut/fill will be provided to this reference and design cross-slope and long slope will update to reflect the height reference selected.

Workflow 03: Offset a model reference

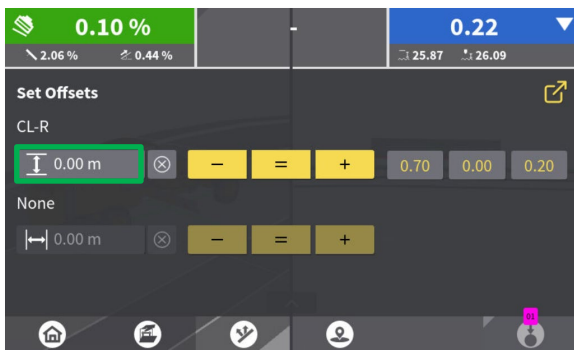
When working outside of auto range limit, offsetting the reference model allows you to utilize automatics, and thus work more efficiently. Set height offset within "auto range limit". As the surface is being worked, the cut/fill values will reduce to zero as the grade approaches design elevation. Height offsets are used in relation to the machine's height tool point.



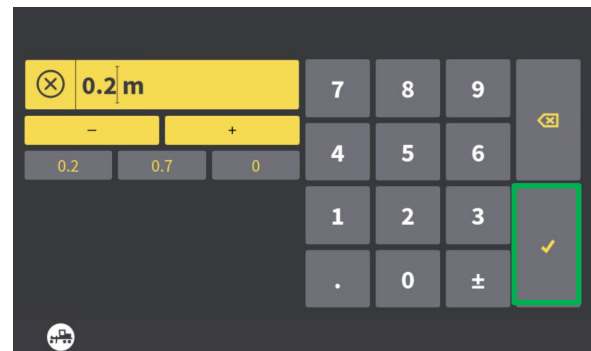
Step 1: Press the "Offset" menu icon.



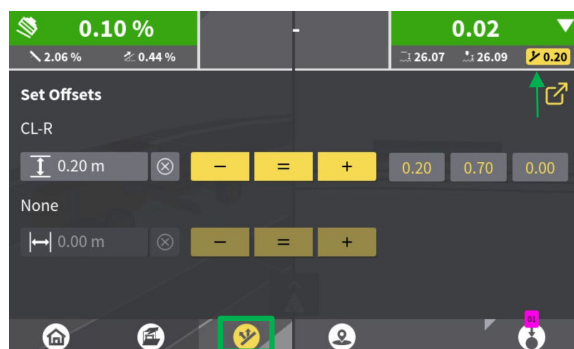
Step 2: Press - or + to offset your design by increments. Select = to set offset to current tool point height.



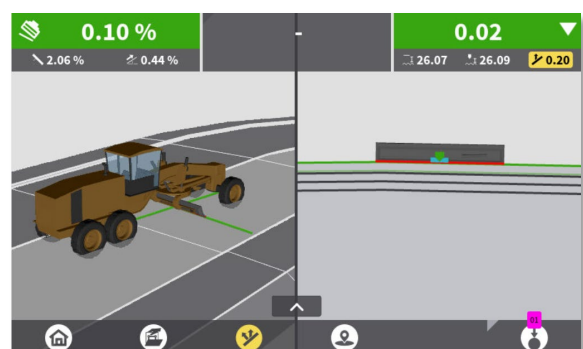
Step 3: Alternatively, press the grey "Height offset" box for a specific offset value input. Latest used offsets are available for quick selection as well.



Step 4: Use keypad to input a value. A list of the last height offset values are listed for quick selection. Press check mark icon to accept value.



Step 5: The offset value will be shown as a small yellow box and the offset icon will turn yellow to indicate an active offset. Press the offset menu icon to return to run screen.



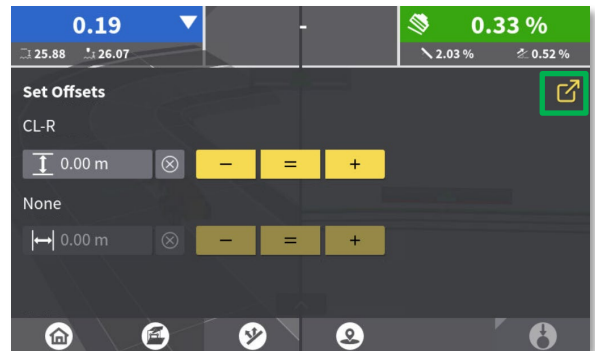
- Cut/fill values will be shown, providing guidance to new height offset. Original grade will still be shown in cross-section with applied offset.

Workflow 04: Offset individual references

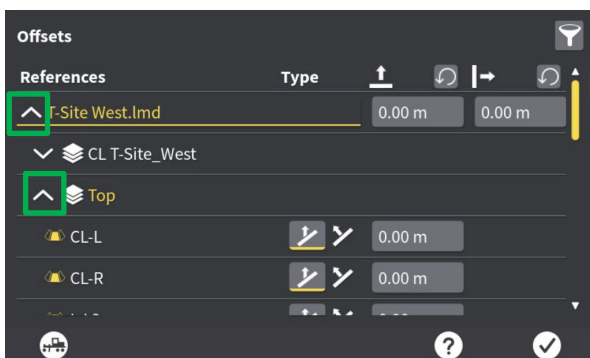
In the expanded “Offsets” menu, you can offset individual references within a model. Only references and models eligible for height/side reference have the option to edit an offset value. Offsets are used in relation to the machine's tool point. Described workflow reflects Individual height offset, but the same workflow applies for individual side reference.



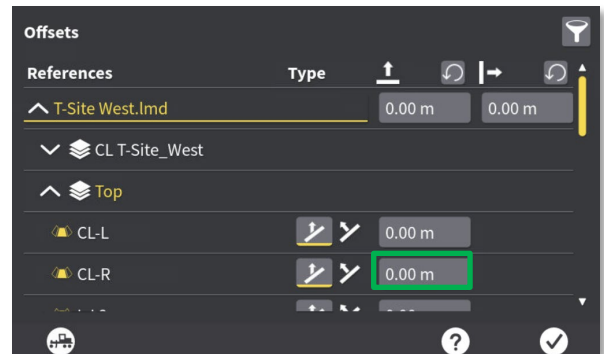
Step 1: Press the “Offsets” menu icon.



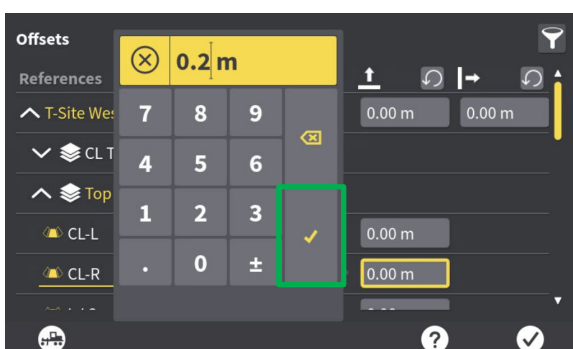
Step 2: Press the expansion button.



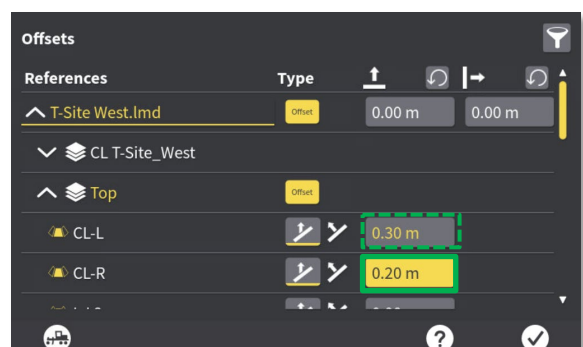
Step 3: Here you have a list of all the referential models. Press the expansion arrow and a height and/or side offset can be applied to individual references.



Step 4: Press the grey box next to a reference to set an offset (height offset for CL-R highlighted here).

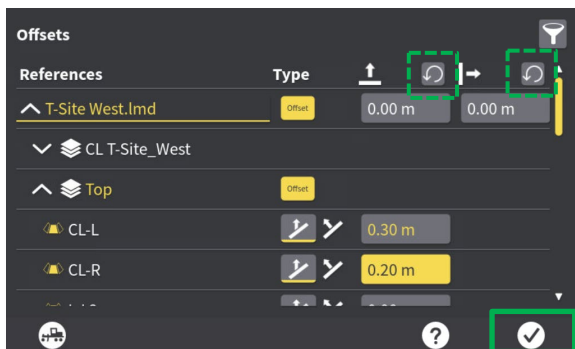


Step 5: Use the keypad to input a value and press tick mark to confirm.



- The current active offset is highlighted in a yellow box, whereas other offsets are written in yellow text.

Workflow 04: Offset individual references (continued)



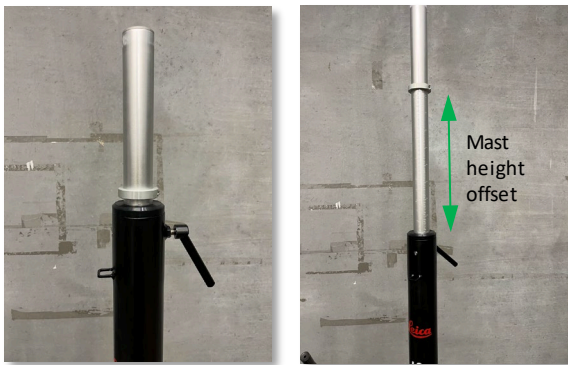
Step 6: The "revert" buttons at the top can be pressed to remove offset values for all references. Press tick mark icon to return to run screen.



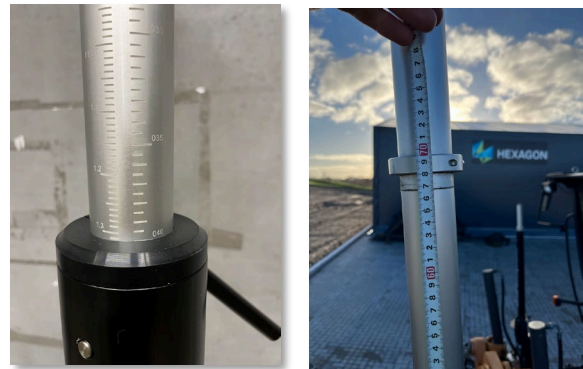
- Cut/fill values will be shown, providing guidance to new height offset. Original grade will still be shown in cross-section with applied offset.

Workflow 05: Enter temporary mast height

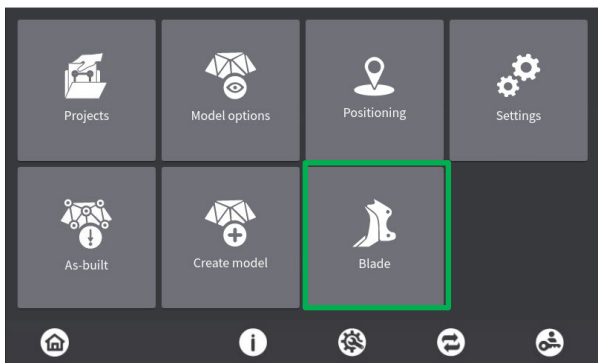
When mounting a prism on the mast you can increase the mast height above the cabin, so the cabin does not block the line of sight when using TPS. This workflow describes how to adjust the mast height and where to enter the offset values in MC1.



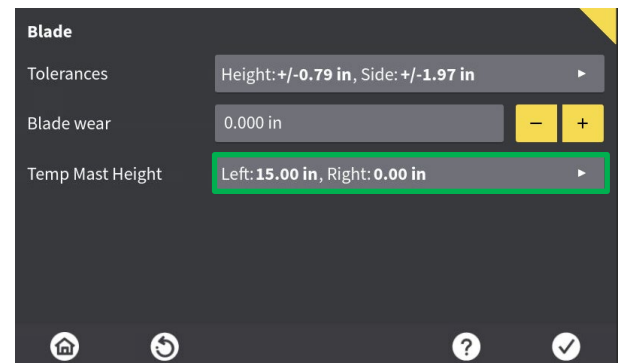
Step 1: Adjust the height on your mast.



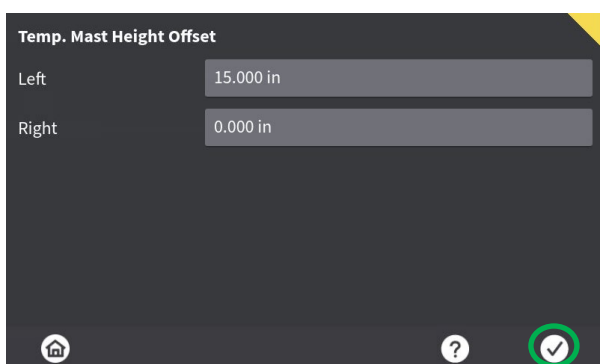
Step 2: Read the offset height directly on the mast or measure with a ruler. Note down the measurement.



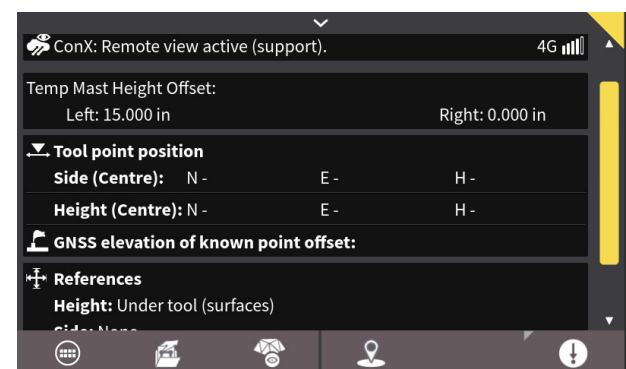
Step 3: Press "Blade" in the main menu.



Step 4: Press the temp mast height menu. If offset values are entered, you can see them here. It is not mandatory to mount or enter offset values for both masts.



Step 5: Enter the offset values measured in step 2 for the relevant mast. Leave the value 0.000 in for any masts you have not raised. Press the tick mark two times to return to the main menu. Return to this menu, when you lower your mast and change the offset value back to 0.000 in.



Step 6: Verify the entered off set values by opening the run screen pull up menu. We recommend verifying the tool point position with a known point of reference.

Workflow 06: Change "height tool point"

The height tool point defines where MC1 looks for elevation guidance, when a height "reference" is selected. Note: changing the height tool point may lead to significant hydraulic reaction on the blade, it is recommended to change while not in auto.

The "up" and "down" hard keys on the MCP80 panel toggle active height tool point.



- Height tool points are represented by a "green" icon on the blade (Left height tool point is shown).



Step 1: Press "up" hard key to toggle height tool point to middle position.



Step 2: Press "up" hard key to toggle height tool point to right tip position.



Step 3: Press "down" hard key to toggle height tool point in opposite direction.

Workflow 07: Change "side tool point"

The side tool point defines where MC1 looks for horizontal guidance, when a side "reference" is selected.

The "left" and "right" hard keys on the MCP80 panel toggle active side tool point.



- Side tool points are represented by a "teal" icon on the blade (Left side tool point is shown).



Step 1: Press "right" hard key to toggle side tool point to middle position.



Step 2: Press "right" hard key to toggle side tool point to right tip position.



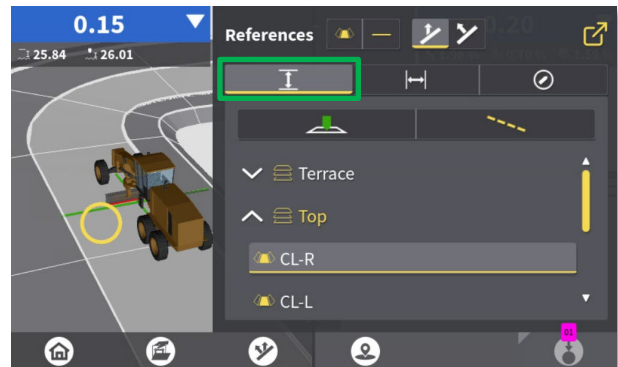
Step 3: Press "left" hard key to toggle side tool point in opposite direction.

Workflow 08: Select and use a "height reference"

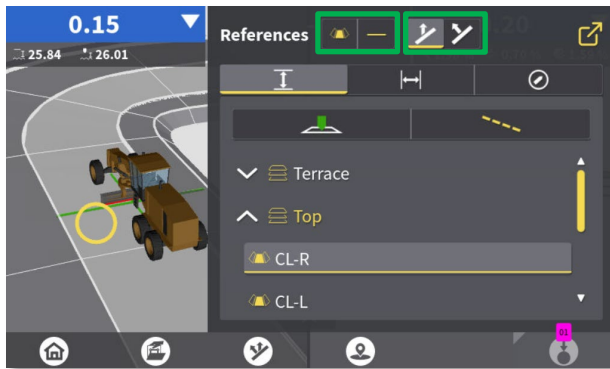
From the run screen, you can select and use different parts of your model as "height reference". The "height tool point" defines where MC1 looks at the model for elevation guidance. Understanding how this works is useful in different grading applications where you might need to overhang one part of your design to cut another. See Workflow 09 for how to select and use "side reference".



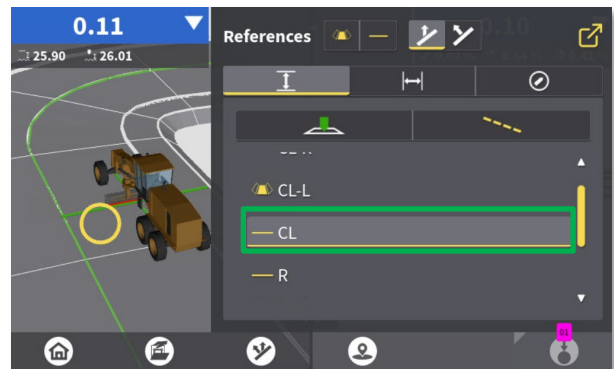
Step 1: Press and hold on plan view to see the "References" menu.



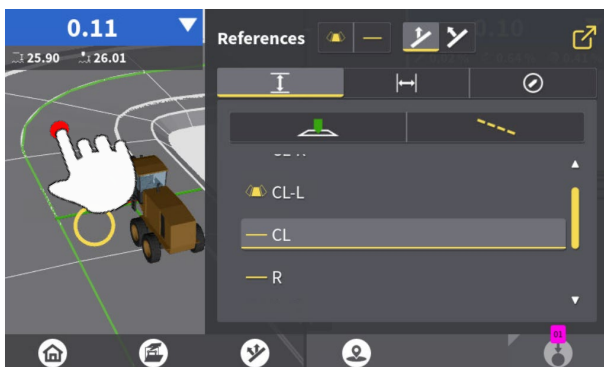
Step 2: Press **I** icon to view height references (if not already highlighted).



- It is possible to filter references (surfaces/lines) and to choose between a vertical or perpendicular height reference.



Step 3: Select the desired height reference (line "leftside" shown here). The line closest to selected point is listed at the top.



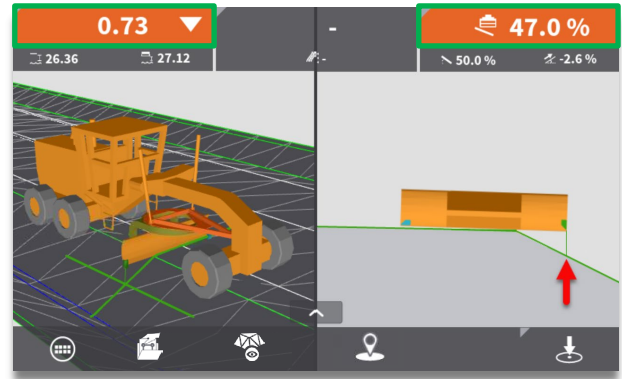
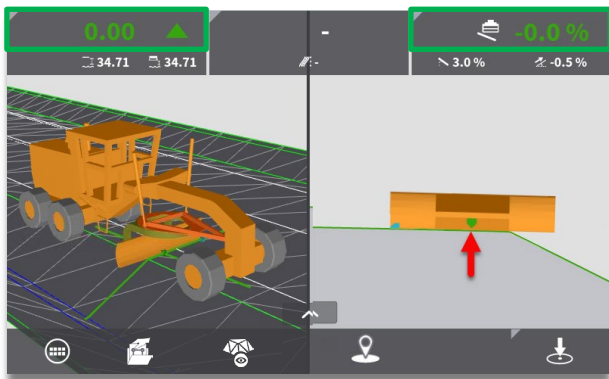
Step 4: Tap anywhere in the plan view to exit the "References" menu.



- The new surface will be represented by a bold green line. Cut/fill will be provided to this reference and design cross-slope and long slope will update to reflect the height reference selected.

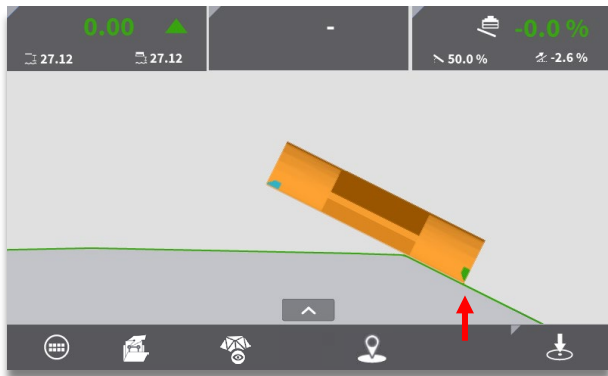
Workflow 08: Select and use a height reference (continued)

Example of the impact of the location of the height tool point:



- Cut/fill and slope values are based on the surface below current height tool point (Middle height tool point shown).

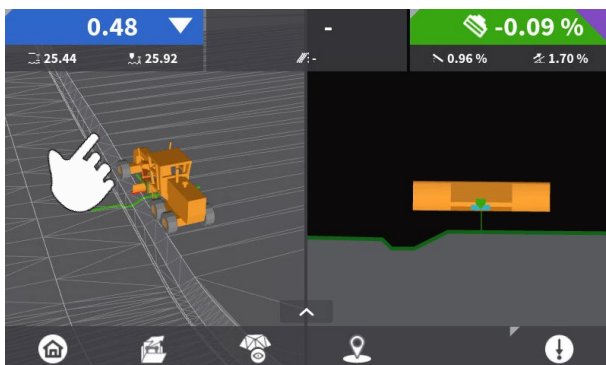
- When design slope changes under current height tool point, cut/fill and slope values also change (Right height tool point shown).



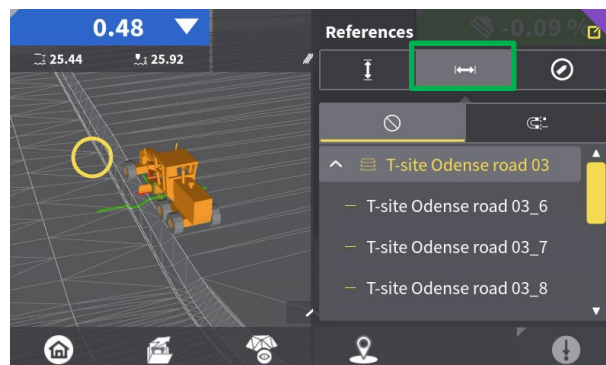
- Blade shown in correct position to grade surface under current height tool point.


Workflow 09: Select and use a "side reference"

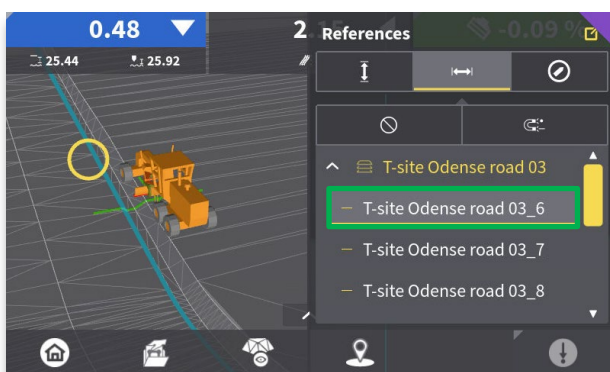
From the run screen, you can select and use different parts of your model as "side reference". The "side tool point" defines where MC1 looks at the model for horizontal guidance. Select a point or line, and you will see a navigation bar at the top of the run screen. This navigation bar will guide you to the selected reference, based on your active side tool point. See Workflow 08 for how to select and use "height reference".



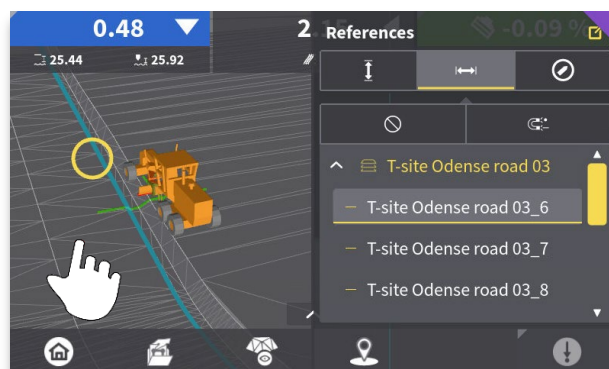
Step 1: Press and hold on plan view to see the "References" menu.



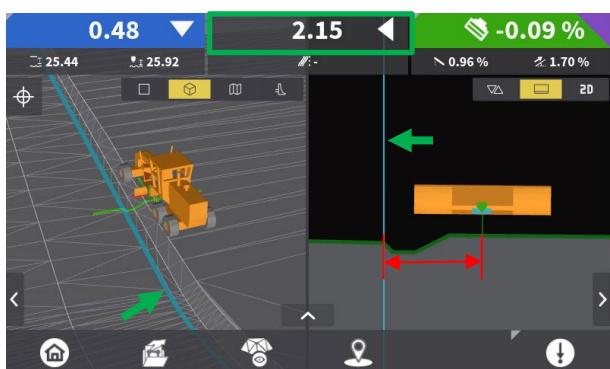
Step 2: Press  icon to view side references.



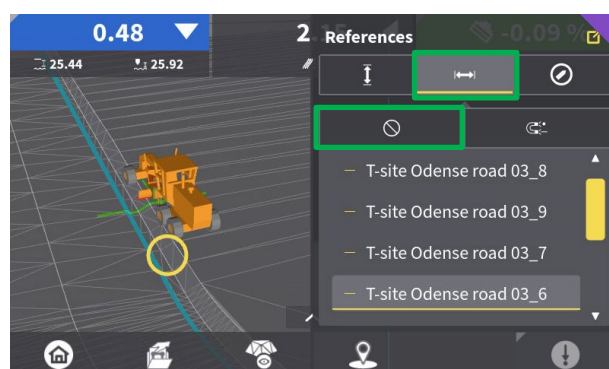
Step 3: Select desired line reference (line "leftside" shown here). The line closest to selected point is listed at the top.




Step 4: Tap anywhere in the plan view to exit the "References" menu.



- The offset distance, from current side tool point to selected line reference, is shown at top centre of the screen. A teal line represents selected line in run screen.



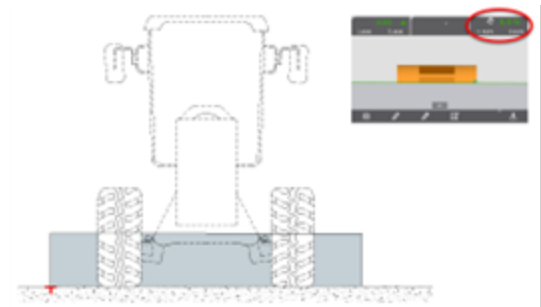
- To clear the side reference, press and hold on run screen, press  icon and select "None" to clear the side reference line.

Workflow 10: Daily machine check-in

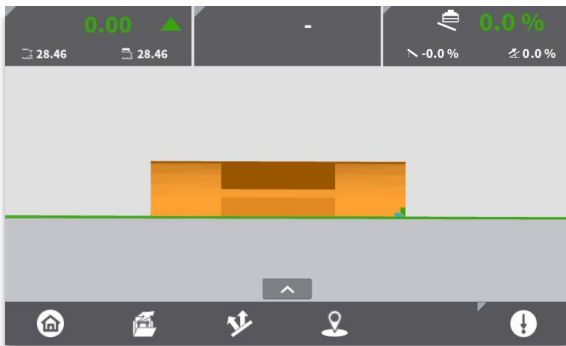
An ideal control point, used for machine check-in, is positioned in an area that will not be disturbed for the duration of the project. The location should allow for the machine to be level in cross slope, and the blade should be level. Use of a spotter on the ground is recommended to position the blade precisely.



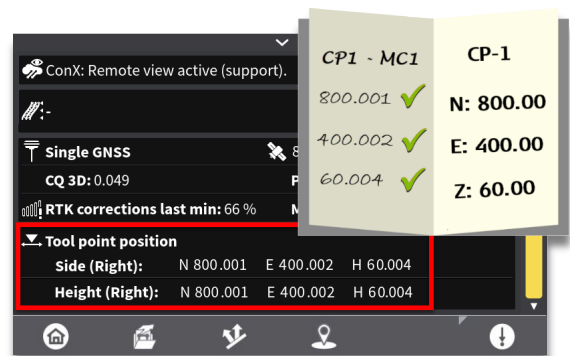
Step 1: Position used tool point at control point.



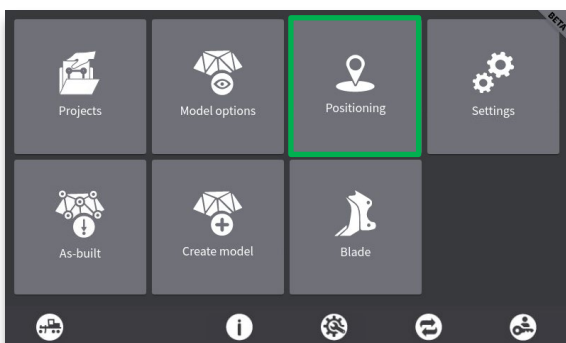
Step 2: Ensure blade is level, and that slope values are 0%.



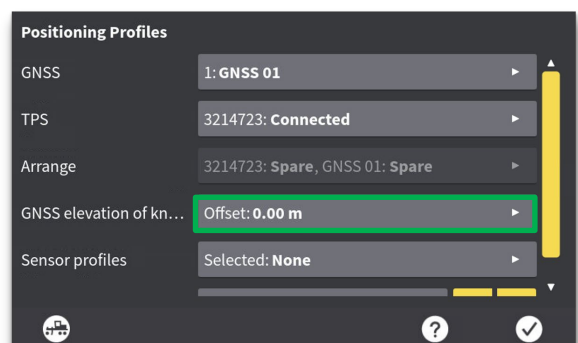
Step 3: Use "up/down" and "left, right" keys to place both "height" and "side" tool points at the desired tip of blade and select "iCON" info bar.



Step 4: Compare tool point position to control point (CP) coordinates.



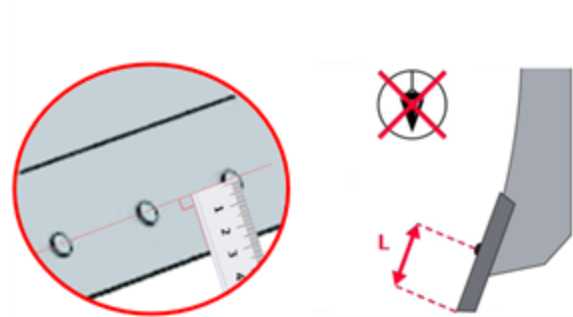
Step 5: If necessary, use the feature "GNSS elevation of known point" from "Main menu > Positioning".



Step 6: If your elevation offset is more than 10cm (.328 feet), please call your machine tech for assistance.

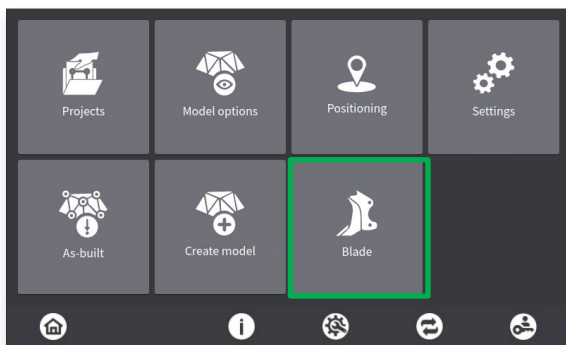
Workflow 11: Adjust blade wear

Check for blade wear regularly. The cutting edge of your machine is designed to be replaceable, and the rate in which it wears depends upon the material it is working with. Incorrect measurement of blade wear can result in incorrect guidance. If the blade wear is uneven, measure a few spots along the cutting edge to find an average, or find the most representative place for a single measurement, avoiding the outer 0.5m of the blade.

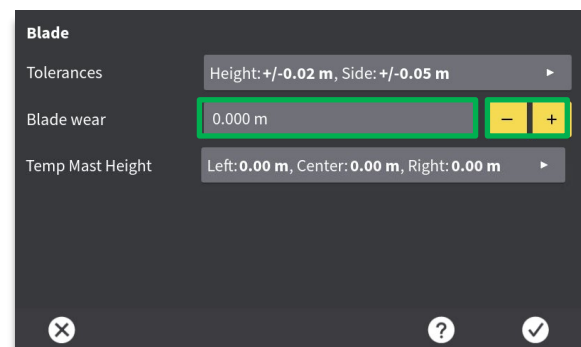


Step 1: Select a representative area of the cutting edge to measure blade wear (Avoid the outer .05m of the blade).

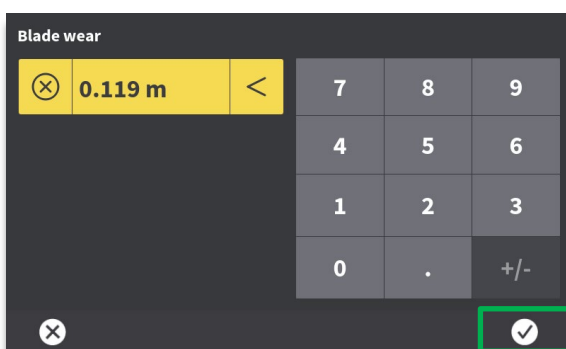
Step 2: Measure flat against surface of cutting edge to centre of bolt holes. This value represents your current blade wear.



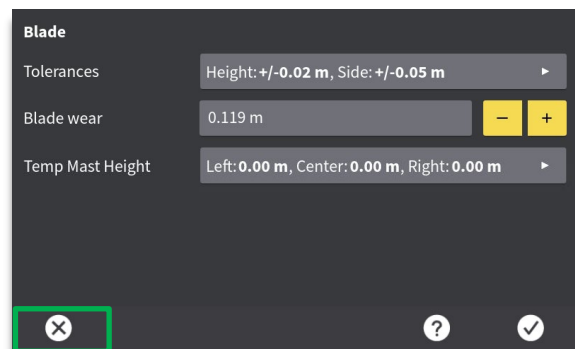
Step 3: Select "Blade" menu.



Step 4: Use + or - keys to increment blade wear value, or select the number to input manually.



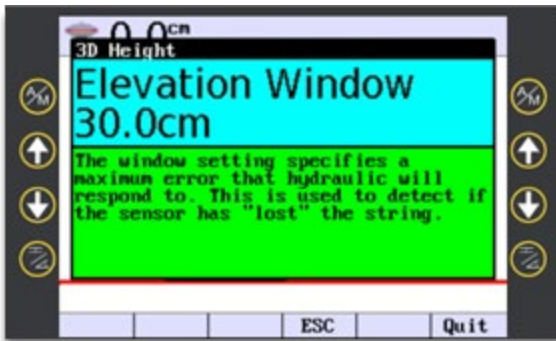
Step 5: Use keypad to enter blade wear value manually. Press "OK" to accept.



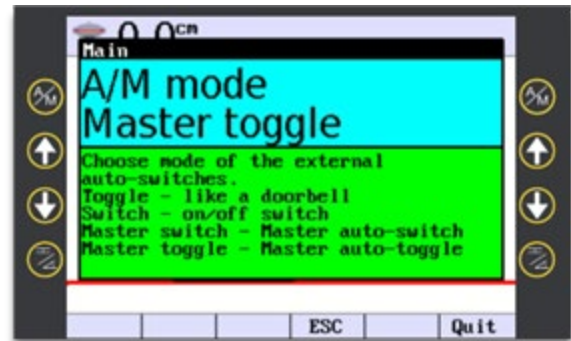
Step 6: Press "X" to exit to return to run screen.

Workflow 12: Activate auto mode

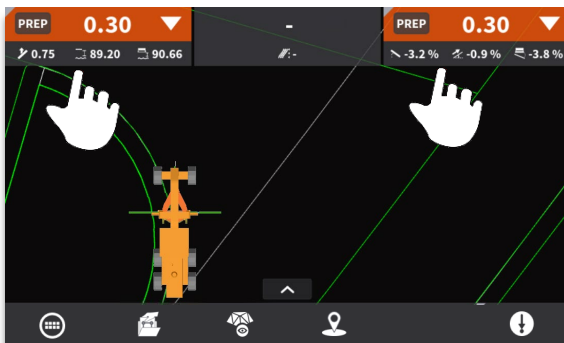
If your machine is equipped with automatic functionality you can activate automatic blade control, when the blade is within a specified distance from the design. When in "auto", the blade will attempt to achieve 0.00 cut/fill. Please ensure your machine is pushing material when "auto" is engaged.



- "3D Height Elevation Window" is set in the 2D UI > Configure > Adjust > Right 3x. If outside this window Auto will not engage. Suggested value is 30cm (0.98') typically set by technician.



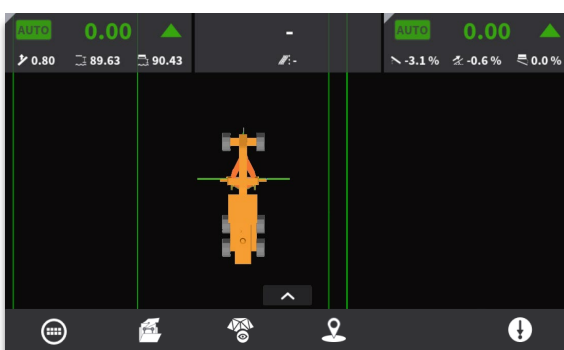
- There are multiple Auto/Manual mode Toggle functions to select from, typically set by technician.



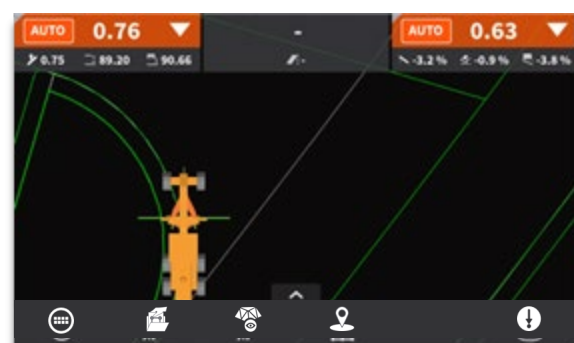
Step 1: Press and hold cut/fill on each side to get PREP to appear (This step is not necessary if set to A/M Mode: Toggle).



Step 2: Press installed "auto" button, to engage automatic control of the blade.



- When "auto" is engaged, top left and right guidance bars show "AUTO" in green, and blade attempts to achieve 0.00 cut/fill.



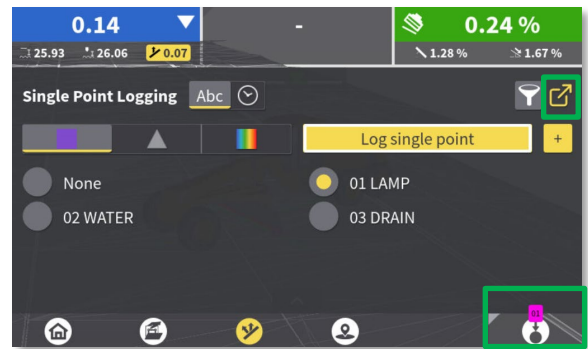
- If the blade is raised outside of the configured elevation window, the system will go into red (inactive auto)

Workflow 13: Create point logs

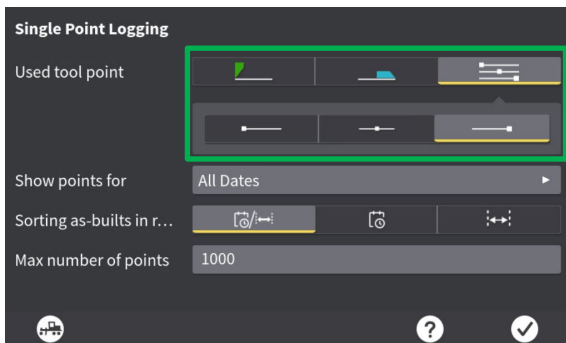
You can log points on your design, from the run screen. Apply a user defined point log, or select from a predefined point log. MC1 can automatically send stored points to ConX (if connected to ConX).



Step 1: Press “Log point” button to quickly log a point.



Step 2: Press and hold “Log point” button. Select a point code from available point code list and press “Log point” button to log a point with that point code. For more options select quick access button in top right corner.



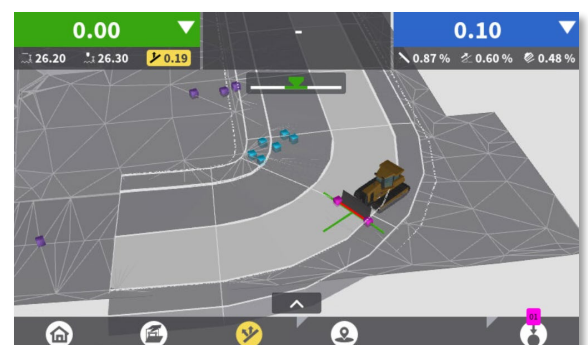
Step 3: Choose which tool point to use when logging a point (current height tool point, current side tool point or specific tool point not used for height or side references). Press grader icon to return to run screen.



Step 4: Press “Log point” button to log a point. The label on top of the “log point” button will correspond the point code you have selected.



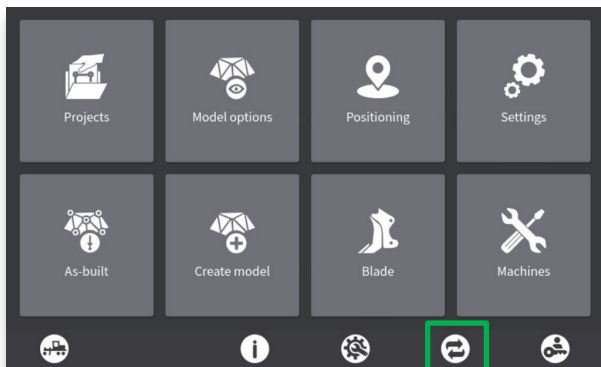
Step 5: If necessary, press “Revert” to remove previously logged point. You also have the option to add a comment to your point.



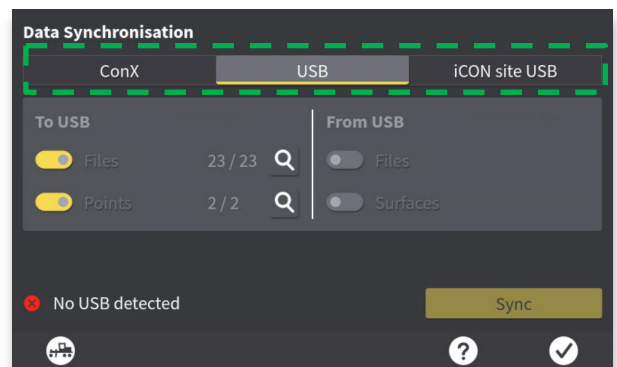
- If configured, previously stored points will appear in the plan view as coloured dots.

Workflow 14: Synchronise files

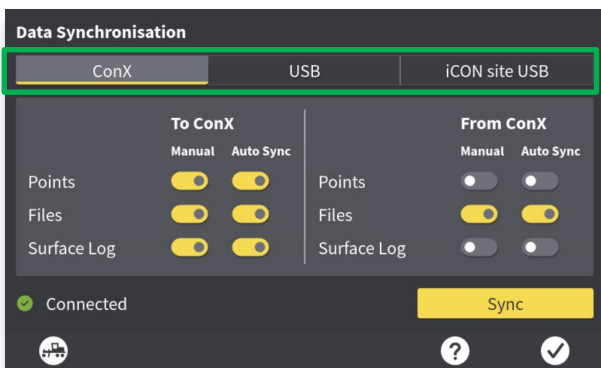
Files can be synchronised to and from ConX, a USB key and iCON site both manually and automatically. This way you can send and receive files between machine and office. You need a valid ConX license and a USB key to perform the synchronisation.



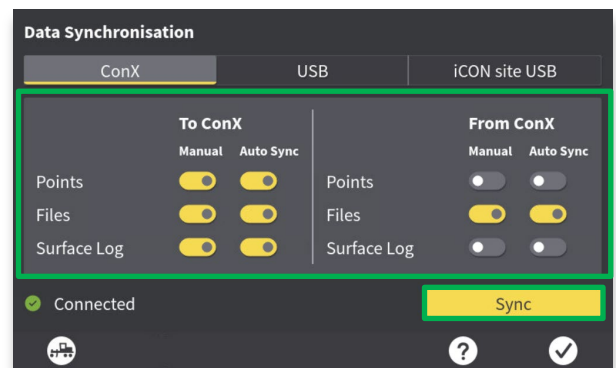
Step 1: Press the synchronisation button.



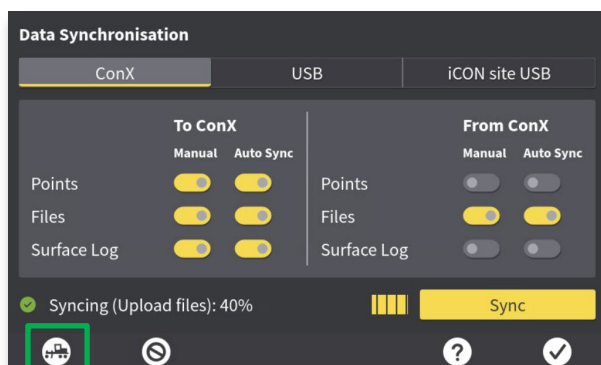
- Selection of possible synchronisation methods. “USB” is only selectable with an inserted USB key in the panel.



Step 2: Select desired synchronisation method. ConX is connected and therefore available for sync.



Step 3: Select which data type under “To ConX” and “From ConX” to synchronise either manually or automatically. Press “Sync” to start manual synchronisation.



- Synchronisation progress will be indicated on the screen. If you want to continue working while ConX syncs, you can press the machine icon to return to run screen or any other page (a pop-up message will inform you when the sync is completed).

Appendix: List of "how to" videos

Use this link <https://leicageosystems.how/usingMC1dozergrader> or the QR code below to access a wide selection of "how to" videos that will help you get the most out of your work with MC1 for grader:



The following is a selection of the currently available videos:

- Using dozer and grader run screens.
- How to set up 3D sensor profiles.
- How to select a predefined coordinate system.
- Engage a project.
- How to engage with surface models.
- How to engage with string line models.
- Multiple surfaces model.
- Select a stationing line.
- Run screen settings.
- Using hold slope – an advanced feature.
- Auto point logging.
- Calibrate your cross slope sensor.
- Adjust for blade wear.
- Setting tolerances and beep settings.
- Single Point Logging.
- Pairing TPS.
- ...many more videos will be added.